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A canonical system of differential equations arising from the Riemann zeta-function

By

Masatoshi SUZUKI *

Abstract

This paper has two main results, which relate to a criteria for the Riemann hypothesis via the family of functions $\Theta_\omega(z) = \xi(\frac{1}{2} - \omega - iz) / \xi(\frac{1}{2} + \omega - iz)$, where $\omega > 0$ is a real parameter and $\xi(s)$ is the Riemann xi-function. The first main result is necessary and sufficient conditions for Θ_ω to be a meromorphic inner function in the upper half-plane. It is related to the Riemann hypothesis directly whether Θ_ω is a meromorphic inner function. In comparison with this, a relation of the Riemann hypothesis and the second main result is indirect. It relates to the theory of de Branges, which associates a meromorphic inner function and a canonical system of linear differential equations (in the sense of de Branges). As the second main result, the canonical system associated with Θ_ω is constructed explicitly and unconditionally under the restriction of the parameter $\omega > 1$ by applying a method of J.-F. Burnol in his recent work on the gamma function to the Riemann xi-function. If such construction is extended to all $\omega > 0$ unconditionally, we get a criterion for the Riemann hypothesis in terms of a family of canonical systems parametrized by $\omega > 0$, which explains the validity of the Riemann hypothesis as positive semidefiniteness of the corresponding family of Hamiltonian matrices.

§ 1. Introduction

Let $\zeta(s)$ be the Riemann zeta function. The set of all non-trivial zeros of the Riemann zeta function coincides with the set of all zeros of the Riemann xi-function

$$\xi(s) = \frac{1}{2} s(s-1) \pi^{-s/2} \Gamma\left(\frac{s}{2}\right) \zeta(s).$$

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*Department of Mathematics, Tokyo Institute of Technology, 2-12-1 Ookayama, Meguro-ku, Tokyo 152-8551, Japan.

e-mail: msuzuki@math.titech.ac.jp

The Riemann hypothesis, which is often abbreviated to RH, assert that all zeros of $\xi(s)$ lie on the critical line $\Re(s) = 1/2$. We attempt to understand the nontrivial zeros of the Riemann zeta function via the family of functions

$$(1.1) \quad A^\omega(z) := \frac{1}{2}(\xi(s + \omega) + \xi(s - \omega)), \quad B^\omega(z) := \frac{i}{2}(\xi(s + \omega) - \xi(s - \omega)),$$

where $s = 1/2 - iz$ and ω is a positive real parameter. Functions $A^\omega(z)$ and $B^\omega(z)$ take real values on the real line and satisfy the functional equations $A^\omega(z) = A^\omega(-z)$ and $B^\omega(z) = -B^\omega(-z)$ by the functional equations $\xi(s) = \xi(1 - s)$ and $\xi(s) = \overline{\xi(\bar{s})}$.

If all zeros of $A^\omega(z)$ lie on the real line for every $\omega > 0$, it implies RH by Hurwitz's theorem in complex analysis. Conversely, all zeros of $A^\omega(z)$ lie on the real line for $\omega \geq 1/2$ unconditionally and for $0 < \omega < 1/2$ under RH by a result of Lagarias [15] (see also Li [21] for an unconditional result for $0 < \omega < 1/2$). We abbreviate to $\text{RH}(A^\omega)$ (resp. $\text{RH}(B^\omega)$) the assertion that all zeros of $A^\omega(z)$ (resp. $B^\omega(z)$) lie on the real line, and abbreviate $\text{RH}(A^\omega)$ and $\text{RH}(B^\omega)$ as $\text{RH}(A^\omega, B^\omega)$. Then the above things are stated as follows:

Proposition 1.1. *RH holds if and only if $\text{RH}(A^\omega)$ holds for all $\omega > 0$.*

The latter condition is easier to study in that it is currently known to hold for all $\omega \geq 1/2$. Also it is known to be related to some operators. We will study the latter problem of finding linear differential equation systems with boundary conditions for which the zeros of $A^\omega(z)$ are eigenvalues, for a suitable range of ω .

It is believed that a promising way to prove RH is the Hilbert-Pólya conjecture which asserts that the non-trivial zeros of the Riemann zeta function correspond to eigenvalues of some positive operator if RH is true. Therefore, if we refer to Proposition 1.1, it is an interesting problem to find a canonical way realizing the zeros of $A^\omega(z)$ as the eigenvalues of some positive operator. Fortunately, as shown in [15] (see also [16]), it is possible for $\omega \geq 1/2$ unconditionally and for $0 < \omega < 1/2$ under RH if we use the theory of de Branges spaces that are kind of reproducing kernel Hilbert spaces consisting of entire functions. However, unfortunately, RH is used essentially in [15] to construct corresponding de Branges spaces for $0 < \omega < 1/2$.

According to a general theory of de Branges spaces, there exists a unique canonical system of linear differential equations associated with a given de Branges space up to a normalization. And also, it is known that a special class of canonical system is transformed into a pair of Schrödinger equations endowed with a pair of (distributional) potentials. At this stage, the validity of $\text{RH}(A^\omega)$ is encoded in analytic properties of potentials (see [16], and also [17]). Hence, a possible way to avoid assuming RH in the construction of the de Branges space arising from $A^\omega(z)$ for $0 < \omega < 1/2$ is a direct construction of a pair of potentials without RH. However, in general, it is difficult to

determine a pair of potentials corresponding to a given de Branges space, and it is so for the de Branges space arising from $A^\omega(z)$ even if $\omega \geq 1/2$.

A goal of the present paper is to describe unconditionally for $\omega > 1$, a canonical system and corresponding pair of potentials associated with a de Branges space arising from $A^\omega(z)$ in terms of Fredholm determinants of certain compact integral operators (Theorem 2.3). The restriction $\omega > 1$ is expected to be relaxed to $\omega > 0$ if RH is true (see comments after Theorem 2.3 and Section 5 for details).

In order to explain the above things more precisely, we review results on de Branges spaces, canonical systems and model subspaces.

§ 1.1. de Branges spaces and canonical system

At first, we review the theory of de Branges spaces according to de Branges [9] and Lagarias [16, 17] (see also Remling [24]). Let E be an entire function satisfying the Hermite-Biehler condition

$$(1.2) \quad |E(z)| > |E^\sharp(z)| \quad \text{for } \Im(z) > 0,$$

where $E^\sharp(z) = \overline{E(\bar{z})}$. Then entire function E generates the de Branges space

$$B(E) := \{f \mid f \text{ is entire, } f/E \text{ and } f/E^\sharp \in H^2\}$$

endowed with norm $\|f\|_{B(E)} := \|f/E\|_{L^2(\mathbb{R})}$, where $H^2 = H^2(\mathbb{C}^+)$ is the Hardy space in the upper half-plane \mathbb{C}^+ which is defined to be the space of all analytic functions f in \mathbb{C}^+ endowed with norm $\|f\|_{H^2}^2 := \sup_{v>0} \int_{\mathbb{R}} |f(u + iv)|^2 du < \infty$. An entire function $F(z)$ is called a *real entire function* if $F(z) = F^\sharp(z) (= \overline{F(\bar{z})})$. Condition (1.2) implies that real entire functions

$$A(z) := \frac{1}{2}(E(z) + E^\sharp(z)), \quad B(z) := \frac{i}{2}(E(z) - E^\sharp(z))$$

have real zeros only, and these zeros interlace. Moreover, if $E(z) \neq 0$ on the real line, all zeros are simple ([8, Lemma 5]). A de Branges space $B(E)$ has an unbounded operator $(M, \mathfrak{D}(M))$, multiplication by the independent variable $(Mf)(z) = zf(z)$ with the domain $\mathfrak{D}(M) = \{f \in B(E) \mid zf(z) \in B(E)\}$. The multiplication operator M is symmetric and closed, and if $\mathfrak{D}(M)$ is dense in $B(E)$, it has deficiency indices $(1, 1)$, and hence has a family of self-adjoint extensions M_θ parametrized by $\theta \in [0, \pi)$. In particular, $M_{\pi/2}$ and M_0 have pure discrete spectrum located at zeros of $A(z)$ and $B(z)$ respectively.

We put the normalization $E(0) = 1$ for entire functions E satisfying (1.2) for a convenience. Then, for a given de Branges space $B(E)$, there exists a chain of de Branges spaces $B(E_a) \subset B(E)$, $0 < a \leq c (\leq \infty)$, endowed with a family of entire functions $E_a(z)$ satisfying (1.2) and $E_a(0) = 1$ such that $B(E_a) \subset B(E_{a'})$ for $a < a'$,

and the parametrized pair of real entire functions $(A_a, B_a) := (\frac{1}{2}(E_a + E_a^\sharp), \frac{i}{2}(E_a - E_a^\sharp))$ satisfies the *canonical system*

$$\frac{\partial}{\partial a} \begin{bmatrix} A_a(z) \\ B_a(z) \end{bmatrix} = z \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} H(a) \begin{bmatrix} A_a(z) \\ B_a(z) \end{bmatrix}, \quad H(a) = \begin{bmatrix} \alpha(a) & \beta(a) \\ \beta(a) & \gamma(a) \end{bmatrix}$$

of linear differential equations with the initial condition

$$\lim_{a \rightarrow 0^+} (A_a(z), B_a(z)) = (1, 0)$$

for each $z \in \mathbb{C}$, and $E_c(z) = E(z)$ (see [9, Theorem 40], but note that it is formulated in terms of integral equations). Here the matrix $H(a)$ is a *measurable* and *real positive semidefinite symmetric* matrix for almost all $0 < a \leq c$, and which is integrable over the interval. The matrix $H(a)$ is often called a Hamiltonian of a canonical system. These properties of $H(a)$ are crucial, because the initial function E can be recovered from $H(a)$ by solving the canonical system with the above initial condition ([9, Theorem 41]). On the other hand, the spectrum of the extended multiplication operator M_θ coincides with the spectrum of the above canonical system with the boundary condition $\lim_{a \rightarrow 0^+} (A_a(z), B_a(z)) = (1, 0)$ and $A_c(z) \sin \theta - B_c(z) \cos \theta = 0$.

If $H(a)$ is diagonal ($\beta(a) = 0$) and $\alpha(a)\gamma(a) = 1$ almost everywhere in $(0, c]$, the corresponding canonical system is transformed into a pair of Schrödinger equations

$$\left(-\frac{d^2}{da^2} + V^\pm(a) \right) \psi(a, z) = z^2 \psi(a, z), \quad V^\pm(a) = \frac{1}{4} \left(\frac{\alpha'(a)}{\alpha(a)} \right)^2 \pm \frac{1}{2} \left(\frac{\alpha'(a)}{\alpha(a)} \right)',$$

and the initial E is recovered by solving the pair of Schrödinger equations under the corresponding initial conditions.

Eventually, condition (1.2) of E is encoded in analytic properties of $H(a)$ or $V^\pm(a)$. In general, it is difficult to determine $H(a)$ or $V^\pm(a)$ for given E except for few special examples (see Chapter 3 of [9], and also [17, 6]).

§ 1.2. Spectral realization of zeros of A^ω and B^ω

Suppose that the condition

$$(1.3) \quad |\xi(s + \omega)| > |\xi(s - \omega)| \quad \text{for } \Re(s) > \frac{1}{2}$$

holds. Then we find that $E(z) = E^\omega(z) := \xi(\frac{1}{2} + \omega - iz)$ satisfies (1.2) by using the functional equations $\xi(s) = \xi(1 - s)$ and $\xi(s) = \overline{\xi(\bar{s})}$. Thus the de Branges space $B(E^\omega)$ is defined, and $\text{RH}(A^\omega, B^\omega)$ holds. By a result of [15], condition (1.3) holds for $\omega \geq 1/2$ unconditionally and for $0 < \omega < 1/2$ under RH. This is the reason why RH implies $\text{RH}(A^\omega)$ for all $\omega > 0$. However, for fixed $\omega > 0$, condition (1.3) is only a sufficient

condition to $\text{RH}(A^\omega, B^\omega)$, that is, $\text{RH}(A^\omega)$ or $\text{RH}(B^\omega)$ may be true even if condition (1.3) does not hold.

Anyway, we can regard the zeros of $A^\omega(z)$ and $B^\omega(z)$ as discrete spectrum of self-adjoint extensions of $(M, \mathfrak{D}(M))$ on $B(E^\omega)$ for $\omega \geq 1/2$ unconditionally and for $0 < \omega < 1/2$ under RH. Therefore, a natural problem on $\text{RH}(A^\omega)$ and a spectral realization of the zeros of $A^\omega(z)$ is to find a way avoiding RH for $0 < \omega < 1/2$. A possible approach is to construct $H(a)$ or $V^\pm(a)$ associated with $B(E^\omega)$ without assuming RH, and recover E^ω , A^ω and B^ω from the canonical system attached to $H(a)$ or the pair of Schrödinger equations attached to $V^\pm(a)$. We attempt to follow this way by using the theory of model subspaces.

§ 1.3. Model subspaces

For further discussions, we review a theory of model spaces according to Havin–Mashreghi [12, 13] (see also Baranov [1], Makarov–Poltoratski [22]). A function Θ is called an *inner function* in \mathbb{C}^+ if it is a bounded analytic function in \mathbb{C}^+ such that $\lim_{v \rightarrow 0^+} |\Theta(u + iv)| = 1$ for almost all $u \in \mathbb{R}$ with respect to Lebesgue measure. If an inner function Θ in \mathbb{C}^+ is extended to a meromorphic function in \mathbb{C} , it is called a *meromorphic inner function* in \mathbb{C}^+ . It is known that every meromorphic inner function is expressed as $\Theta = E^\sharp/E$ by using an entire function E satisfying (1.2). For an inner function Θ , a *model subspace* (or coinvariant subspace) $K(\Theta)$ is defined by the orthogonal complement

$$(1.4) \quad K(\Theta) = H^2 \ominus \Theta H^2,$$

where $\Theta H^2 = \{\Theta(z)F(z) \mid F \in H^2\}$. It has the alternative representation

$$(1.5) \quad K(\Theta) = H^2 \cap \Theta \bar{H}^2,$$

where $\bar{H}^2 = H^2(\mathbb{C}^-)$ is the Hardy space in the lower half-plane \mathbb{C}^- . If Θ is a meromorphic inner function such that $\Theta = E^\sharp/E$, the model subspace $K(\Theta)$ is isomorphic to the de Branges space $B(E)$ as a Hilbert space by $K(\Theta) \rightarrow B(E) : f \mapsto fE$. In particular, $K(\Theta)$ is a reproducing kernel Hilbert space. The reproducing kernel of $K(\Theta)$ is given by

$$(1.6) \quad K(z, w) = \frac{1}{2\pi i} \frac{1 - \overline{\Theta(z)}\Theta(w)}{\bar{z} - w} \quad (z, w \in \mathbb{C}^+),$$

and the reproducing formula $f(z) = \langle f, K(z, \cdot) \rangle_{L^2(\mathbb{R})}$ ($f \in K(\Theta)$, $z \in \mathbb{C}^+$) remains true for $z \in \mathbb{R}$ if Θ is analytic in a neighborhood of u , where $\langle f, g \rangle_{L^2(\mathbb{R})} = \int_{\mathbb{R}} f(u)\overline{g(u)}du$.

§ 1.4. Model subspaces related to A^ω and B^ω

Now we apply the theory of model subspaces to the spaces $B(E^\omega)$ of Section 1.2. For positive real ω , we define the meromorphic function $\Theta_\omega(z)$ in \mathbb{C} by

$$(1.7) \quad \Theta_\omega(z) := \frac{\xi(\frac{1}{2} - \omega - iz)}{\xi(\frac{1}{2} + \omega - iz)}.$$

Then we have

$$(1.8) \quad \Theta_\omega(z)\Theta_\omega(-z) = 1 \quad \text{for } z \in \mathbb{C},$$

$$(1.9) \quad |\Theta_\omega(u)| = 1 \quad \text{for } u \in \mathbb{R},$$

$$(1.10) \quad \Theta_\omega(0) = 1,$$

by functional equations $\xi(s) = \xi(1 - s)$ and $\xi(\bar{s}) = \overline{\xi(s)}$.

The inequality (1.3) can now be reinterpreted as the condition

$$(1.11) \quad |\Theta_\omega(z)| < 1 \quad \text{for } \Im(z) > 0$$

and vice versa. Recall that condition (1.3) is known to hold for $\omega \geq 1/2$ unconditionally and for $0 < \omega < 1/2$ under RH. By (1.9), when condition (1.11) holds, it implies that $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ . Therefore, whenever (1.11) holds, we obtain a model subspace $K(\Theta_\omega)$ which is isomorphic to the de Branges space $B(E^\omega)$ generated by $E^\omega(z) = \xi(\frac{1}{2} + \omega - iz)$. Here we mention the following equivalence relation.

Proposition 1.2. *Let $\omega_0 \geq 0$. Then the following are equivalent:*

- (1) $\zeta(s) \neq 0$ for $\Re(s) > \frac{1}{2} + \omega_0$,
- (2) $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ for every $\omega > \omega_0$.

Proof. Assume that $0 \leq \omega_0 < 1/2$ since we have nothing to say for $\omega \geq 1/2$. By applying Theorem 4 of [18], we find that (1) implies that (1.11) holds for every $\omega > \omega_0$. Thus we obtain (1) \Rightarrow (2). The converse implication (2) \Rightarrow (1) is proved by a way similar to the proof of Theorem 2.3 (1) in [26]. □

The changing of consideration from $B(E^\omega)$ to $K(\Theta_\omega)$ has the advantage that spaces $\Theta_\omega H^2$, $\Theta_\omega \bar{H}^2$, $H^2 \ominus (H^2 \cap \Theta_\omega H^2)$ and $H^2 \cap \Theta_\omega \bar{H}^2$ are defined even if $\Theta_\omega(z)$ is not necessarily a meromorphic inner function in \mathbb{C}^+ (see (1.4) and (1.5)), and it allows us to study these spaces for the range $0 < \omega < 1/2$ without assuming RH. (Note that

$\Theta H^2 \not\subset H^2$ in general if Θ is not necessary a inner function in \mathbb{C}^+ .) To make a further discussion, we use Fourier analysis.

§ 1.5. An operator related to $K(\Theta_\omega)$

As usual we identify H^2 and \bar{H}^2 with subspaces of $L^2(\mathbb{R}) = L^2((-\infty, \infty), du)$ via nontangential boundary values on the real line such that $L^2(\mathbb{R}) = H^2 \oplus \bar{H}^2$. Then the shifted Fourier transform

$$\begin{aligned} F_{1/2} : L^2((0, \infty), dx) &\rightarrow L^2(\mathbb{R}) : (F_{1/2}f)(z) = \int_0^\infty f(x) x^{\frac{1}{2}+iz} \frac{dx}{x}, \\ F_{1/2}^{-1} : L^2(\mathbb{R}) &\rightarrow L^2((0, \infty), dx) : (F_{1/2}^{-1}g)(z) = \frac{1}{2\pi} \int_{-\infty}^\infty g(u) x^{-\frac{1}{2}-iu} du \end{aligned}$$

provides an isometry of L^2 -spaces up to a constant such that $H^2 = F_{1/2}L^2((1, \infty), dx)$ and $\bar{H}^2 = F_{1/2}L^2((0, 1), dx)$ by the Paley-Wiener theorem.

Fourier analysis on $K(\Theta_\omega)$ and $\Theta_\omega H^2$ enables us to state equivalent or sufficient conditions that $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ (Theorem 2.2).

On the other hand, condition (1.9) allows us to define the Hankel type operator

$$(H_\omega^* f)(x) = \int_0^\infty h_\omega^*(xy) f(y) dy$$

on $L^2((0, \infty), dx)$ endowed with the kernel given by

$$(1.12) \quad h_\omega^*(x) = \frac{1}{2\pi} \int_{-\infty}^\infty \Theta_\omega(u) x^{-\frac{1}{2}-iu} du.$$

Of course the definition of H_ω^* has only a formal sense because of the problem of the convergence of integral in (1.12). However $h_\omega^*(x)$ is going to be identified with the function $h_\omega(x)$ in Section 2, and then H_ω^* is going to be justified as the operator H_ω obtained by replacing the kernel $h_\omega^*(x)$ by $h_\omega(x)$. Moreover the operator H_ω is extended to an isometry from $L^2((0, \infty), dx)$ to $L^2((0, \infty), dx)$ for $\omega \geq 1/2$ unconditionally, and for $0 < \omega < 1/2$ under RH (see Lemma 4.1).

As developed in Burnol [6] (and his other related works [3, 4, 5]), the Hankel type operator H_ω and its kernel $h_\omega(xy)$ is quite useful to study a structure of subspaces of $F_{1/2}^{-1}K(\Theta_\omega)$ corresponding to de Branges subspaces of $B(E^\omega) \simeq K(\Theta_\omega)$. By applying Burnol's theory to H_ω and $h_\omega(x)$, we derive a canonical system of $B(E^\omega)$ under the restriction $\omega > 1$ (Theorem 2.3 and studying in Section 4). Recall that the structure of subspaces of a de Branges space is controlled by its canonical system.

§ 1.6. Summary of issues

Briefly, we have two issues. The first is to state a (nice) criterion for the innerness of $\Theta_\omega(z)$. It is directly related to the zero-free region of $\zeta(s)$ (Proposition 1.2). The

second is to describe the Hamiltonian $H_\omega(a)$ of the canonical system of $B(E^\omega)$ explicitly by assuming that $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ if $0 < \omega < 1/2$. If it is done, we can state that $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ if and only if $(A^\omega, B^\omega) = (A_c, B_c)$ for the solution (A_a, B_a) of the canonical system for $H_\omega(a)$ on $a \in (0, c]$ satisfying $\lim_{a \rightarrow 0^+} (A_a, B_a) = (E^\omega(0), 0)$. This description explains the innerness of $\Theta_\omega(z)$ as a consequence of properties of $H_\omega(a)$, and it provides a criterion for a zero-free region of $\zeta(s)$ in terms of a family of canonical systems attached to $\{H_\omega(a)\}_{\omega > \omega_0}$ via Proposition 1.2.

However the second problem is not trivial even if $\omega \geq 1/2$. In this paper, we deal with the case $\omega > 1$ for the second problem as the first attempt.

§ 1.7. Organization of the paper

The paper is organized as follows. In Section 2, we state main results Theorem 2.2 and Theorem 2.3 after a small preparation of notation. The first one is equivalent conditions on the Hermite-Biehler condition (1.11) in terms of the function $h_\omega(x)$ for fixed $\omega > 0$. This is proved in Section 3. The second one is a result on the canonical system of $B(E^\omega) \simeq K(\Theta_\omega)$ under the restriction $\omega > 1$. It is proved in Section 4 together with related studies and auxiliary results. In addition, we present more sufficient or equivalent conditions that $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ in Appendix A (Theorem A.1).

Here we mention that this paper, particularly Appendix A, is a sequel to [26], though it is independent and can be read separately. The operator H_ω^* of Section 1.5 is also justified as the Watson transform:

$$(H_\omega^{**} f)(x) = \frac{d}{dx} \int_0^\infty h_\omega^{**}(xy) f(y) \frac{dy}{y}, \quad h_\omega^{**}(x) = \frac{1}{2\pi} \int_{-\infty}^\infty \frac{\Theta_\omega(u)}{\frac{1}{2} - iu} x^{\frac{1}{2} - iu} du,$$

which gives a linear involution on $L^2((0, \infty), dx)$ under (1.8) (only for real z) and (1.9) (see Titchmarsh [28, §8.5], Bochner–Chandrasekharan [2, Chap.V, §2]). Moreover, $H_\omega^{**} = H_\omega$ if $\Theta_\omega(z)$ is inner in \mathbb{C}^+ . The Watson transform has the advantage that $h_\omega^{**}(x)$ always exists in L^2 -sense by (1.9), and belongs to $L^2((0, \infty), dx)$. While the modified function

$$h_\omega^{(1)}(x) = \frac{1}{2\pi} \int_{-\infty}^\infty \frac{\Theta_\omega(u)}{-iu} x^{\frac{1}{2} - iu} du$$

does not belong to $L^2((0, \infty), dx)$ although it is justified as a function (Appendix A). However it is also useful to study the space $K(\Theta_\omega)$ and the operator H_ω because of formula (1.6) for the reproducing kernel. In fact, several sufficient or equivalent conditions that $\Theta_\omega(z)$ is inner in \mathbb{C}^+ are stated in terms of $h_\omega^{(1)}(x)$ (Theorem A.1) as well as

Theorem 2.2. Moreover, if $\Theta_\omega(z)$ is inner in \mathbb{C}^+ , we obtain

$$(H_\omega f)(x) = \int_0^\infty h_\omega(xy) f(y) dy = \sqrt{x} \frac{d}{dx} \sqrt{x} \int_0^\infty h_\omega^{(1)}(xy) f(y) dy$$

for compactly supported smooth functions f , and it is extended to $L^2((0, \infty), dx)$ (Theorem A.2). The function $h_\omega^{(1)}(x)$ was introduced and studied in [26] for more general L -functions, but a relation with spaces $B(E^\omega) \simeq K(\Theta_\omega)$ and operators H_ω were not mentioned there. In this sense, this paper is a sequel to [26].

§ 1.8. De Branges' works

Finally, we comment on de Branges' works on $B(E^\omega)$. The de Branges space $B(E^\omega)$ was considered first for the special value $\omega = 1/2$ in de Branges [10, pp.10–14], motivating to generalize the Lax-Phillips scattering theory to the Laplace-Beltrami operator, and for $\omega \geq 1/2$ in the subsequent paper [11, pp.205–210]. (Precisely, we need to replace $\zeta(s)$ by a Dirichlet L -function $L(s, \chi)$ attached to an even primitive Dirichlet character χ in [10]). De Branges gave a sufficient condition on $B(E)$ attached to general entire function E satisfying (1.2) such that the zeros of $E(z)$ lie on the line $\Im(z) = -1/2$, which implies the (generalized) RH when $E = E^\omega$ for $\omega = 1/2$. However Conrey and Li [7] showed that $B(E^\omega)$ ($\omega = 1/2$) does not satisfy de Branges' condition. For $\omega \geq 1/2$ de Branges studied the space $B(E^\omega)$ by associating it with the weighted Hardy space $\mathcal{F}(W) = WH^2$ for the weight function $W(z) = \frac{1}{4}(s + \omega)(s + \omega - 1)\Gamma(\frac{s+\omega}{2})$ with $s = \frac{1}{2} - iz$, but we omit the details of this topic (see [11], and also [7]).

In any case, de Branges directly related RH with a condition on $B(E^\omega)$ for fixed $\omega \geq 1/2$. On the other hand, we reduced RH to the family of spaces $\{B(E^\omega)\}_{\omega>0}$, and study each space $B(E^\omega)$ depending on a level of difficulty, which is determined by the value ω . This is a major difference with de Branges' approach and ours.

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§ 2. Main Results

Our first result is to derive an expression for $\Theta_\omega(z)$ as a Mellin transform of a function $h_\omega(x)$ defined for $0 < x < \infty$, which is valid for all real $\omega > 0$ (Proposition 2.1). To define this function we first define the numbers

$$(2.1) \quad c_\omega(n) := n^\omega \sum_{d|n} \frac{\mu(d)}{d^{2\omega}} = n^\omega \prod_{p|n} \left(1 - \frac{1}{p^{2\omega}}\right)$$

for natural numbers n , where $\mu(n)$ is the Möbius function, that is, $\mu(n) = 0$ if n is not a square free number, and $\mu(n) = (-1)^k$ if n is a product of k distinct primes. The arithmetic function $n \mapsto J_{2\omega}(n) := n^\omega c_\omega(n)$ is called Jordan's totient function, which gives Euler's totient function $\varphi(n)$ for $\omega = 1/2$.

Next we introduce a function $g_\omega(x)$ defined on $(0, \infty)$ by

$$g_\omega(x) = \frac{2\pi^\omega}{\Gamma(\omega)} \left(x^{2-\omega} (1-x^2)^{\omega-1} - \omega x^{\omega-1} \int_{x^2}^1 t^{\frac{1}{2}-\omega} (1-t)^{\omega-1} dt \right)$$

for $0 < x < 1$, and $g_\omega(x) = 0$ for $x > 1$. It is continuous on $(0, 1)$ and $(1, \infty)$. The behavior of g_ω near $x = 1$ and $x = 0$ is as follows. We have

$$(2.2) \quad g_\omega(x) = \frac{(2\pi)^\omega}{\Gamma(\omega)} (1-x)^{\omega-1} + o(1) \quad \text{as } x \rightarrow 1^-.$$

Therefore g_ω is continuous at $x = 1$ if and only if $\omega > 1$, and it is L^1 (resp. L^2) at $x = 1$ if $\omega > 0$ (resp. $\omega > 1/2$). On the other hand, we have

$$g_\omega(x) = \begin{cases} -4\omega\pi^{\omega-1/2}\Gamma(3/2-\omega)x^{\omega-1} + o(1), & 0 < \omega < 3/2, \\ 4\pi\sqrt{x}(3\log x + 4 - 3\log 2) + o(1), & \omega = 3/2, \\ -6\pi^\omega(2\omega-3)^{-1}\Gamma(\omega)^{-1}x^{2-\omega} + o(1), & \omega > 3/2, \end{cases} \quad \text{as } x \rightarrow 0^+.$$

Thus g_ω is L^1 (resp. L^2) at $x = 0$ if $0 < \omega < 3$ (resp. $1/2 < \omega < 5/2$). The size of the singularity at $x = 1$ will be important in the sequel because it influences the type of operators $H_{\omega,a}$ below, while there is no need to be careful about the behavior around $x = 0$ in this paper.

Finally, we define the real-valued function h_ω on $(0, \infty)$ by

$$(2.3) \quad h_\omega(x) = \frac{1}{x} \sum_{n=1}^{\lfloor x \rfloor} c_\omega(n) g_\omega\left(\frac{n}{x}\right)$$

for $x > 1$, and $h_\omega(x) = 0$ for $0 < x < 1$. The value $h_\omega(1)$ may be undefined, since $c_\omega(1) = 1$ and $g_\omega(1^-) = +\infty$ for $0 < \omega < 1$ by (2.2). By definition, h_ω has a support in $[1, \infty)$, and is L^1 (resp. L^2) on every finite interval $[1, b]$ if $\omega > 0$ (resp. $\omega > 1/2$). On the other hand, the behavior of h_ω at $x = +\infty$ is not obvious from its definition (see (4.22) below). Now the first result is stated as follows.

Proposition 2.1. *For $\omega > 0$ and $\Im(z) > 1/2 + \omega$, we have*

$$(2.4) \quad \int_0^\infty h_\omega(x) x^{\frac{1}{2}+iz} \frac{dx}{x} = \Theta_\omega(z),$$

where the integral converges absolutely.

We introduce more notation in order to state the main results mentioned in the introduction. By (1.9), $F(z) \mapsto \Theta_\omega(z)F(z)$ defines a map $L^2(\mathbb{R}) \rightarrow L^2(\mathbb{R})$. We denote it also by Θ_ω if no confusion arises, and define

$$\widehat{\Theta}_\omega = F_{1/2}^{-1} \Theta_\omega F_{1/2} : L^2((0, \infty), dx) \rightarrow L^2((0, \infty), dx).$$

If $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ , images $\Theta_\omega H^2$ and $\widehat{\Theta}_\omega L^2((1, \infty), ds)$ are subspaces of H^2 and $L^2((1, \infty), dx)$, respectively. Obviously the map $\widehat{\Theta}_\omega$ is related to the function h_ω by (2.4). In fact the innerness of $\Theta_\omega(z)$ is described in terms of h_ω as follows.

Theorem 2.2. *Let $\omega > 0$. The function $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ if and only if one of the following conditions holds:*

(1) $\widehat{\Theta}_\omega f = h_\omega * f$ for every $f \in L^2((1, \infty), dx)$, where

$$(h_\omega * f)(x) = \int_0^\infty h_\omega(x/y) f(y) \frac{dy}{y}.$$

(2) $\widehat{\Theta}_\omega f$ vanishes on $(0, 1)$ for every $f \in L^2((1, \infty), dx)$.

(3) $h_\omega * f$ belongs to $L^2((0, \infty), dx)$ for every $f \in L^2((1, \infty), dx)$.

Suppose that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ . Then

$$(2.5) \quad (\mathbf{H}_\omega f)(x) = \int_0^\infty h_\omega(xy) f(y) dy$$

defines a bounded operator from $L^2((0, \infty), dx)$ to $L^2((0, \infty), dx)$ (Lemma 4.1). For $a > 0$, we denote by \mathbf{P}_a the orthogonal projection from $L^2((0, \infty), dx)$ to $L^2((0, a), dx)$, and define

$$(2.6) \quad \mathbf{H}_{\omega,a} := \mathbf{P}_a \mathbf{H}_\omega \mathbf{P}_a : L^2((0, a), dx) \rightarrow L^2((0, a), dx).$$

A study of \mathbf{H}_ω and $\mathbf{H}_{\omega,a}$ yields a canonical system as follows:

Theorem 2.3. *Suppose that $\omega > 1$. (It implies automatically that Θ_ω is inner in \mathbb{C}^+ .) Then the operator $\mathbf{H}_{\omega,a}$ is a Hilbert-Schmidt type self-adjoint operator with a continuous kernel for every $a > 1$, and $\mathbf{H}_{\omega,a} = 0$ for $0 < a \leq 1$. Moreover $1 \pm \mathbf{H}_{\omega,a}$ are invertible for every $a > 0$. Define*

$$m(a) := m_\omega(a) = \frac{\det(1 + \mathbf{H}_{\omega,a})}{\det(1 - \mathbf{H}_{\omega,a})}$$

by using Fredholm determinants. Then $m(a)$ is real-valued continuous function on $(0, \infty)$, and the canonical system

$$-a \frac{\partial}{\partial a} \begin{bmatrix} X_a(z) \\ Y_a(z) \end{bmatrix} = z \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} m(a)^{-2} & 0 \\ 0 & m(a)^2 \end{bmatrix} \begin{bmatrix} X_a(z) \\ Y_a(z) \end{bmatrix} \quad (0 < a < \infty)$$

has the explicit solution $(X_a, Y_a) = (A_a, B_a)$ given by (4.26) in Section 4 such that

- (1) $A_a(z)$ and $B_a(z)$ are real entire functions as a function of z for every fixed $a > 0$,
- (2) $A_a(-z) = A_a(z)$ and $B_a(-z) = -B_a(z)$ as a function of z for every fixed $a > 0$,
- (3) $(A_1(z), B_1(z)) = (A^\omega(z), B^\omega(z))$ and

$$\lim_{a \rightarrow 1^+} (A_a(z), B_a(z)) = \lim_{a \rightarrow 1^-} (A_a(z), B_a(z)) = (A^\omega(z), B^\omega(z))$$

hold uniformly on every compact subset in \mathbb{C} , where $A^\omega(z)$ and $B^\omega(z)$ are real entire functions defined in (1.1).

Furthermore, the canonical system can be transformed into the pair of Schödinger equations

$$\left(-a \frac{\partial}{\partial a} a \frac{\partial}{\partial a} + V^\pm(a)\right) \psi^\pm(a, z) = z^2 \psi^\pm(a, z)$$

with the pair of potentials

$$V^\pm(a) = \left(\frac{1}{m(a)} a \frac{\partial}{\partial a} m(a)\right)^2 \mp a \frac{\partial}{\partial a} \left(\frac{1}{m(a)} a \frac{\partial}{\partial a} m(a)\right)$$

by taking $\psi^+(a, z) = m^{-1}(a)A_a(z)$ and $\psi^-(a, z) = m(a)B_a(z)$.

The assumption $\omega > 1$ in Theorem 2.3 is required to obtain a continuity of the kernel $h_\omega(xy)$ in the proof in Section 4.3 and 4.4, since $h_\omega(x)$ has a singularity at $x = n \in \mathbb{Z}_{>0}$ for $0 < \omega \leq 1$. However, we observed that singularities at $x = n \in \mathbb{Z} > 0$ are in L^2 exactly for $\omega > 1/2$, and are in L^1 for all $\omega > 0$. This implies that the function $h_\omega(x)$ on any interval $[x_0, x_1]$ with $0 < x_0 < x_1 < \infty$ lies in the same function spaces, and it affects the behavior of associated $H_{\omega,a}$. In fact, $H_{\omega,a}$ is a Hilbert-Schmidt type self-adjoint operator such that $1 \pm H_{\omega,a}$ are invertible for every $a > 0$ if $\omega > 1/2$ (Lemma 4.2 and 4.4 below), and is a compact self-adjoint operator for all $\omega > 0$. In addition, the type of singularities at $x = n \in \mathbb{Z} > 0$ presumably affects the canonical system since it is given by determinants of $1 \pm H_{\omega,a}$ if $\omega > 1$.

On the other hand, as mentioned in Section 1.2 and 1.4, $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ for all $\omega \geq 1/2$ unconditionally, and for all $\omega > 0$ under RH.

Therefore, it is plausible that all results of Theorem 2.3 can be extended to $\omega > 1/2$ unconditionally without essential difficulties. Moreover, it is expected that Theorem 2.3 is generalized to $\omega > 0$ if we assume RH for $\zeta(s)$. See Section 5 for further comments on the validity of Theorem 2.3.

Finally, we emphasize that the limit behavior $\lim_{a \rightarrow +\infty} (A_a(z), B_a(z))$ is still open even if $\omega > 1$. The expected result is $\lim_{a \rightarrow +\infty} (E^\omega(0), 0) = (\xi(\frac{1}{2} + \omega), 0)$ if we note that E is normalized as $E(0) = 1$ in Section 1.1. Provably, this limit behavior is related to the arithmetic properties of $\zeta(s)$ in more deep level, because we need information

for all $\{c_\omega(n)\}_{n \geq 1}$ to understand it differ from the situation that we need only finitely many $c_\omega(n)$'s to understand $H_{\omega,a}$ for a finite range of a . However, we do not touch this problem further in this paper.

§ 3. Proof of Proposition 2.1 and Theorems 2.2

§ 3.1. Proof of Proposition 2.1

For convenience, we use variable $s = 1/2 - iz$. Put $\gamma(s) = \frac{1}{2}s(s-1)\pi^{-s/2}\Gamma(s/2)$ so that $\xi(s) = \gamma(s)\zeta(s)$. Then

$$\frac{\gamma(s-\omega)}{\gamma(s+\omega)} = \pi^\omega \frac{\Gamma\left(\frac{s-\omega}{2} + 1\right)}{\Gamma\left(\frac{s+\omega}{2} + 1\right)} - \frac{2\omega\pi^\omega}{s+\omega-1} \frac{\Gamma\left(\frac{s-\omega}{2} + 1\right)}{\Gamma\left(\frac{s+\omega}{2} + 1\right)}.$$

We have

$$(3.1) \quad \frac{\Gamma\left(\frac{s-\omega}{2} + 1\right)}{\Gamma\left(\frac{s+\omega}{2} + 1\right)} = \frac{2}{\Gamma(\omega)} \int_0^1 x^{2-\omega}(1-x^2)^{\omega-1} x^s \frac{dx}{x}$$

for $\Re(s+2) > \omega > 0$ by [23, (5.35) of p.195], and

$$(3.2) \quad \frac{1}{s+\omega-1} = \int_0^1 x^{\omega-1} x^s \frac{dx}{x}$$

for $\Re(s) > 1 - \omega$. Applying Theorem 44 of [28] to (3.1) and (3.2) together with

$$\frac{2}{\Gamma(\omega)} \int_y^1 x^{2-\omega}(1-x^2)^{\omega-1} (y/x)^{\omega-1} \frac{dx}{x} = \frac{y^{\omega-1}}{\Gamma(\omega)} \beta\left(y^2, \frac{3}{2} - \omega, \omega\right),$$

we obtain

$$\int_0^\infty g_\omega(x) x^s \frac{dx}{x} = \int_0^1 g_\omega(x) x^s \frac{dx}{x} = \frac{\gamma(s-\omega)}{\gamma(s+\omega)}$$

for $\Re(s) > \max(\omega - 2, 1 - \omega)$. On the other hand, we have

$$\frac{\zeta(s-\omega)}{\zeta(s+\omega)} = \sum_{m=1}^\infty \frac{\mu(m)m^{-\omega}}{m^s} \sum_{n=1}^\infty \frac{n^\omega}{n^s} = \sum_{n=1}^\infty \frac{1}{n^s} \sum_{d|n} \frac{\mu(d)}{d^\omega} \left(\frac{n}{d}\right)^\omega = \sum_{n=1}^\infty \frac{c_\omega(n)}{n^s}$$

by definition (2.1), where the series converges absolutely for $\Re(s) > 1 + \omega$. By definition (2.3), we have formally

$$\begin{aligned} \int_0^\infty h_\omega(x) x^{1-s} \frac{dx}{x} &= \sum_{n=1}^\infty c_\omega(n) \int_0^\infty x^{-1} g_\omega(n/x) x^{1-s} \frac{dx}{x} \\ &= \sum_{n=1}^\infty \frac{c_\omega(n)}{n^s} \int_0^\infty g_\omega(n/x) (n/x)^s \frac{dx}{x} = \frac{\gamma(s-\omega)}{\gamma(s+\omega)} \frac{\zeta(s-\omega)}{\zeta(s+\omega)}, \end{aligned}$$

and it is justified by Fubini's theorem for $\Re(s) > 1 + \omega$. Replacing s by $1/2 - iz$, we obtain (2.4).

§ 3.2. Proof of Theorem 2.2

It is sufficient to prove the following three assertions:

i) condition (1) is equivalent that Θ_ω is inner in \mathbb{C}^+ , ii) condition (2) implies that Θ_ω is inner in \mathbb{C}^+ , and iii) condition (3) implies that Θ_ω is inner in \mathbb{C}^+ , since (1) implies (2) and (3) by definition of $\widehat{\Theta}_\omega$ and h_ω . We prove them after the following lemma.

Lemma 3.1. *Assume that $\Theta_\omega H^2 \subset H^2$. Then Θ_ω is inner in \mathbb{C}^+ .*

Proof. Let $\delta > 0$. We find that $\Theta_\omega(z)$ is uniformly bounded on the upper half-plane $\Im(z) \geq 1/2 + \omega + \delta$ by using a usual estimate for the Dirichlet series $\zeta(s - \omega)/\zeta(s + \omega)$ and the Stirling formula for the gamma-function. On the other hand, we know (1.9), and the assumption implies that Θ_ω has no poles in \mathbb{C}^+ . Hence, by applying the Phragmén-Lindelöf convexity principle to Θ_ω in the strip $0 \leq \Im(z) \leq 1/2 + \omega + \delta$, we find that Θ_ω is bounded on $0 \leq \Im(z) \leq 1/2 + \omega + \delta$. Therefore Θ_ω is a bounded analytic function in \mathbb{C}^+ satisfying (1.9). This is the definition of an inner function in \mathbb{C}^+ . \square

i) Suppose that Θ_ω is inner in \mathbb{C}^+ . Then $\Theta_\omega F \in H^2$ for every $F \in H^2$. Thus the inverse (shifted) Fourier transform along the line $\Im(z) = c$

$$\widehat{\Theta}_\omega f(x) = \frac{1}{2\pi} \int_{\Im(z)=c} \Theta_\omega(z) F(z) x^{-\frac{1}{2}-iz} dz$$

is independent of $c > 0$, and belongs to $L^2((1, \infty), dx)$, where $f = F_{1/2}^{-1} F$ and the integral converges in the sense of L^2 . On the other hand

$$(h_\omega * f)(x) = \frac{1}{2\pi} \int_{\Im(z)=c'} \Theta_\omega(z) F(z) x^{-\frac{1}{2}-iz} dz$$

for $c' > 1/2 + \omega$ by Proposition 2.1 and [28, Theorem 65], where the integral converges also in the sense of L^2 . Comparing these two formula for large c , we obtain (1).

Conversely, suppose that (1) holds. Write $g = \widehat{\Theta}_\omega f = h_\omega * f$ for arbitrary fixed $f \in L^2((1, \infty), dx)$. Then g belongs to $L^2((0, \infty), dx)$, since $\widehat{\Theta}_\omega$ maps $L^2((0, \infty), dx)$ to $L^2((0, \infty), dx)$ by definition. In addition, g has a support in $[1, \infty)$, since both h_ω and f have support in $[1, \infty)$. Therefore g belongs to $L^2((1, \infty), dx)$. Because f was arbitrary, we have $\Theta_\omega H^2 \subset H^2$. Hence Θ_ω is inner in \mathbb{C}^+ by Lemma 3.1. \square

ii) Suppose that (2) holds. Then it implies $\widehat{\Theta}_\omega L^2((1, \infty), dx) \subset L^2((1, \infty), dx)$, since $\widehat{\Theta}_\omega$ maps $L^2((0, \infty), dx)$ to $L^2((0, \infty), dx)$ by its definition. It means $\Theta_\omega H^2 \subset H^2$ by definition of $\widehat{\Theta}_\omega$. Hence Θ_ω is inner in \mathbb{C}^+ by Lemma 3.1 \square

iii) Suppose that (3) holds. Then $h_\omega * f$ belongs to $L^2((1, \infty), dx)$ for every f in $L^2((1, \infty), dx)$, since $h_\omega * f$ has a support in $[1, \infty)$ by its definition. Therefore

$$\int_0^\infty h_\omega * f(x) x^{\frac{1}{2}+iz} \frac{dx}{x} \in H^2.$$

Additionally, we suppose that f belongs to the dense subset $L^1((1, \infty), dx) \cap L^2((1, \infty), dx)$. Then

$$\int_0^\infty h_\omega * f(x) x^{\frac{1}{2}+iz} \frac{dx}{x} = \Theta_\omega(z)F(z)$$

for $\Im(z) > 1/2 + \omega$ by [28, Theorem 44]. Therefore

$$\widehat{\Theta}_\omega\left(L^1((1, \infty), dx) \cap L^2((1, \infty), dx)\right) \subset L^2((1, \infty), dx),$$

This implies that $\widehat{\Theta}_\omega L^2((1, \infty), dx) \subset L^2((1, \infty), dx)$, since $\widehat{\Theta}_\omega$ is continuous by its definition. Therefore $\Theta_\omega H^2 \subset H^2$ by definition of $\widehat{\Theta}_\omega$, and hence Θ_ω is inner in \mathbb{C}^+ by Lemma 3.1. □

§ 4. Proof of Theorem 2.3

In this section, we study operators (2.5), (2.6), and their kernels toward Theorem 2.3 referring to Burnol [6]. However here we use classical arguments rather than the theory of distributions used in [6].

§ 4.1. Fredholm integral equations

Lemma 4.1. *Suppose that Θ_ω is inner in \mathbb{C}^+ . Define $H_\omega f$ by integral (2.5) for compactly supported smooth functions f . Then $H_\omega f$ belongs to $L^2((0, \infty), dx)$, and the linear map $f \mapsto H_\omega f$ is extended to the isometry $H_\omega : L^2((0, \infty), dx) \rightarrow L^2((0, \infty), dx)$ satisfying*

$$(4.1) \quad (F_{1/2}H_\omega f)(z) = \Theta_\omega(z) (F_{1/2}f)(-z)$$

for $z \in \mathbb{R}$. Moreover, (4.1) holds for $\Im(z) \geq 0$, if $f \in L^2((0, \infty), dx)$ has a support in $[0, b]$ for some $b > 0$.

Remark. This is applied unconditionally to $\omega \geq 1/2$, and also to $0 < \omega < 1/2$ under RH by discussion in Section 1.2 and 1.4.

Proof. If f is a compactly supported smooth function, we have

$$\begin{aligned} (F_{1/2}H_\omega f)(z) &= \int_0^\infty \int_0^\infty h_\omega(xy) x^{\frac{1}{2}+iz} \frac{dx}{x} f(y) dy \\ &= \int_0^\infty h_\omega(y) x^{\frac{1}{2}+iz} \frac{dx}{x} \int_0^\infty f(y) y^{\frac{1}{2}-iz} \frac{dy}{y} = \Theta(z)F(-z) \quad (F = F_{1/2}f) \end{aligned}$$

for $\Im(z) > 1/2 + \omega$ by Proposition 2.1, and $F(-z)$ is an entire function satisfying $F(-z) = O(|z|^{-n})$ as $|z| \rightarrow \infty$ in any horizontal strip $c_1 \leq \Im(z) \leq c_2$ for arbitrary fixed $n > 0$. Therefore, we find that $H_\omega f$ belongs to $L^2((0, \infty), dx)$ by applying the Fourier inversion formula to $\Theta_\omega(z)F(-z)$ along a line $\Im(z) = c > 1/2 + \omega$ and then moving the path of integration to the real line $\Im(z) = 0$, since Θ_ω is inner in \mathbb{C}^+ by assumption. Moreover

$$\|H_\omega f\| = \|\Theta_\omega(\cdot)F(-\cdot)\| = \|F\| = \|f\|$$

by (1.9). Recall that the set of all compactly supported smooth function in $L^2((0, \infty), dx)$ is dense in $L^2((0, \infty), dx)$. Therefore $f \mapsto H_\omega f$ is extended to all $f \in L^2((0, \infty), dx)$ by continuity, and the extended operator is obviously isometric.

Equality (4.1) holds for real z by the continuity. Suppose that $f \in L^2((0, \infty), dx)$ has a support in $[0, b]$ for some $b > 0$. Then $H_\omega f$ belongs to $L^2((0, \infty), dx)$ and has a support in $[1/b, \infty)$. Therefore the left-hand side of (4.1) is defined by the shifted Fourier integral and analytic in \mathbb{C}^+ . On the other hand, $(F_{1/2}f)(-z)$ in the right-hand side of (4.1) is also defined by the shifted Fourier integral and analytic in \mathbb{C}^+ , since f has a support in $[0, b]$ by the assumption. Hence both sides of (4.1) are analytic functions in \mathbb{C}^+ , and they are equal on the real line. Thus equality (4.1) holds for $\Im(z) \geq 0$. \square

Lemma 4.2. *Suppose that $\omega > 1/2$. (It implies automatically that Θ_ω is inner in \mathbb{C}^+ .) Then the operator $H_{\omega,a} = P_a H_\omega P_a$ defined in (2.6) is a self-adjoint Hilbert-Schmidt type operator if $a > 1$, and $H_{\omega,a} = 0$ if $0 < a \leq 1$.*

Proof. If $0 < a \leq 1$ and $0 < x < a$, we have

$$H_\omega P_a f(x) = \int_0^a h_\omega(xy) f(y) dy = 0,$$

since $h_\omega(x) = 0$ for $0 < x < 1$, and $0 \leq xy < a^2 \leq 1$. Hence $H_{\omega,a} = 0$ if $0 < a \leq 1$.

Denote by $K(x, y) = h_\omega(xy)$ the kernel of $H_{\omega,a}$. We have $K(x, y) = \overline{K(y, x)}$, since $h_\omega(xy)$ is real-valued. Thus $H_{\omega,a}$ is self-adjoint. For $a > 1$, we have

$$\begin{aligned} \int_0^a \int_0^a |K(x, y)|^2 dx dy &= \int_{1/a}^a \int_{1/a}^a |h_\omega(xy)|^2 dx dy \\ &\leq \int_{1/a}^a \frac{dy}{y} \int_{1/a^2}^{a^2} |h_\omega(x)|^2 dx = 2 \log a \int_1^{a^2} |h_\omega(x)|^2 dx. \end{aligned}$$

Here $\int_1^{a^2} |h_\omega(x)|^2 dx < \infty$ if $\omega > 1/2$, since $h_\omega(x)$ has only finitely many singularities at $x = n$ ($1 \leq n \leq [a^2]$) in $[1, a^2]$, and $h_\omega(x) \ll |x - n|^{\omega-1}$ around $x = n$ by (2.2) and (2.3). Hence, $K(x, y) = h_\omega(xy)$ is a Hilbert-Schmidt kernel if $a > 1$ and $\omega > 1/2$. \square

Lemma 4.3. *Let $a > 0$. Suppose that $\omega > 1/2$. Then the support of $H_\omega P_a f$ is not compact for $f \in L^2((0, \infty), dx)$ unless $H_\omega P_a f = 0$.*

Proof. We prove this by contradiction. Suppose that $H_\omega P_a f \neq 0$ and has a compact support. Then $F_{1/2} H_\omega P_a f$ is an entire function of exponential type by the Paley-Wiener theorem. On the other hand, we have

$$F_{1/2} H_\omega P_a f(z) = \Theta_\omega(z) \cdot F_{1/2} P_a f(-z).$$

This implies that $G(z) := P_a f(-z) / \xi(\frac{1}{2} + \omega - iz)$ is entire, because (1.2) holds unconditionally for the denominator $E(z) = \xi(\frac{1}{2} + \omega - iz)$ of Θ_ω defined in (1.7), and $E(z) \neq 0$ on $\Im(z) = 0$. Thus, we have

$$F_{1/2} H_\omega P_a f(z) = \xi\left(\frac{1}{2} - \omega - iz\right) \cdot G(z),$$

where the right-hand side is a product of entire functions. The point is that the zeros in the numerator of Θ_ω can not kill the poles of the denominator, which therefore must be killed by zeros of $P_a f(-z)$. This allows $\xi(\frac{1}{2} - \omega - iz)$ to be factored out.

The entire function on the right-hand side has at least $\frac{1}{\pi} T \log T$ zeros in the disk of radius T around the origin, as $T \rightarrow \infty$ ([27, Theorem 9.4]). However all entire functions of exponential type have at most $O(T)$ zeros in the disk of radius T around the origin, as $T \rightarrow \infty$, because of the Jensen formula ([20, §2.5 (15)]). This is a contradiction. (The proof contained an error in the first version, but it was revised by the reviewer.) \square

Lemma 4.4. *Let $\omega > 1/2$ and $a > 1$. We have i) $H_{\omega,a} f = 0$ for every $f \in L^2((0, 1/a), dx)$, ii) $\|H_{\omega,a} f\| < \|f\|$ for every $0 \neq f \in L^2((0, a), dx)$, and iii) $\|H_{\omega,a}\| < 1$. In particular, $1 \pm H_{\omega,a}$ are invertible operator on $L^2((0, a), dx)$.*

Proof. If $0 < x < 1/a$, we have

$$H_\omega P_a f(x) = \int_0^a h_\omega(xy) f(y) dy = 0,$$

since $h_\omega(x) = 0$ for $0 < x < 1$, and $0 \leq xy < 1$. Hence i) is proved.

To prove ii), it is sufficient to show $\|H_{\omega,a} f\| \neq \|f\|$ unless $f = 0$, because $\|H_\omega\| = 1$, $\|H_{\omega,a}\| \leq \|P_a\| \cdot \|H_\omega\| \cdot \|P_a\| = 1$, and $\|H_{\omega,a} f\| \leq \|H_{\omega,a}\| \cdot \|f\| \leq \|f\|$. Here $\|H_{\omega,a} f\| \neq \|f\|$ is equivalent to $\|P_a H_\omega f\| \neq \|f\|$, since $P_a f = f$ for $f \in L^2((0, a), dx)$. Suppose that $\|P_a H_\omega f\| = \|f\|$ for some $0 \neq f \in L^2((0, a), dx)$. Then it implies $\|P_a H_\omega f\| = \|H_\omega f\|$ by $\|H_\omega f\| = \|f\|$. Therefore

$$\int_0^a |H_\omega f(x)|^2 dx = \int_0^\infty |H_\omega f(x)|^2 dx.$$

Thus $H_\omega f(x) = 0$ for almost every $x > a$. On the other hand, we have

$$H_\omega f(x) = \int_0^a h_\omega(xy) f(y) dy = \int_{1/x}^a h_\omega(xy) f(y) dy = 0$$

for $0 < x < 1/a$ by $f \in L^2((0, a), dx)$. Hence $H_\omega f$ has a compact support contained in $[1/a, a]$. However, it is impossible for any $f \neq 0$ by Lemma 4.3. As the consequence $\|H_{\omega,a}f\| < \|f\|$ for $0 \neq f \in L^2((1/a, a), dx)$.

Finally, we prove iii). By Lemma 4.2, $H_{\omega,a}$ is a self-adjoint compact operator. Therefore, $H_{\omega,a}$ has purely discrete spectrum which has no accumulation points except for 0, and one of $\pm\|H_{\omega,a}\|$ is an eigenvalue of $H_{\omega,a}$. However, by ii), every eigenvalue of $H_{\omega,a}$ has an absolute value less than 1. Hence $\|H_{\omega,a}\| < 1$. □

Lemma 4.5. *Let $\omega > 1/2$, $a > 1$ and $\varepsilon \in \{\pm 1\}$. Then the integral equation*

$$(4.2) \quad X(x) + \varepsilon \int_0^a h_\omega(xy)X(y) dy = h_\omega(ax)$$

has unique solution $X = \phi_a^\varepsilon$ in $L^2((0, a), dx)$, which is real-valued almost everywhere in $[0, a]$ and vanishes almost everywhere in $[0, 1/a]$.

Moreover, if $\omega > 1$, the solution ϕ_a^ε is a real-valued continuous function on $[0, a]$ vanishing on $[0, 1/a]$.

Proof. By Lemmas 4.2 and 4.4, $H_{\omega,a}$ is a compact operator such that ± 1 belong to its resolvent set. Therefore, integral equation (4.2) has unique solution ϕ_a^ε in $L^2((0, a), dx)$ by the Fredholm alternative. We have $h_\omega(ax) = 0$ and $\int_0^a h_\omega(xy)\phi_a^\varepsilon(y) dy = 0$ for almost every $0 < x < 1/a$, since $0 < xy < 1$ for $0 < y \leq a$, and $h_\omega(x) = 0$ for $0 < x < 1$.

On the other hand, if $\omega > 1$, the integral $\int_0^a h_\omega(xy)f(y) dy$ defines a continuous function on $[0, a]$ which vanishes on $[0, 1/a]$ for every $f \in L^2((0, a), dx)$, since the kernel $h_\omega(xy)$ is continuous on $[0, a] \times [0, a]$ by (2.2). Hence ϕ_a^ε is continuous on $[0, a]$ and $\phi_a^\varepsilon(x) = 0$ for $0 \leq x \leq 1/a$. Obviously ϕ_a^ε is real-valued, since $h_\omega(x)$ is real-valued, □

Lemma 4.6. *Let $\omega > 1/2$, $a > 1$ and $\varepsilon \in \{\pm 1\}$. Then the integral equation (4.2) has unique extended solution $X = \tilde{\phi}_a^\varepsilon$ in $L^2((0, b), dx)$ for arbitrary $b > a$, which is real-valued almost everywhere in $[0, b]$, and $\tilde{\phi}_a^\varepsilon(x) = \phi_a^\varepsilon(x)$ for almost every $0 < x < a$.*

Moreover, if $\omega > 1$, the integral equation (4.2) has unique extended solution $X = \tilde{\phi}_a^\varepsilon$ in $C^0(0, \infty)$, which is real-valued on $[0, \infty)$ and satisfies $\tilde{\phi}_a^\varepsilon(x) = \phi_a^\varepsilon(x)$ for $0 < x < a$.

Proof. The solution ϕ_a^ε of Lemma 4.5 is extended to the solution $\tilde{\phi}_a^\varepsilon$ on $(0, b)$ by

$$(4.3) \quad \tilde{\phi}_a^\varepsilon(x) = h_\omega(ax) - \varepsilon \int_0^a h_\omega(xy)\phi_a^\varepsilon(y) dy.$$

The right-hand side belongs to $L^2((0, b), dx)$ by the Cauchy-Schwartz inequality, since $h_\omega(x)$ belongs to $L^2((0, b'), dx)$ for every $0 < b' < \infty$ when $\omega > 1/2$ and the integral on the right-hand side vanishes for almost every $0 < x < 1/a$. Clearly, $\tilde{\phi}_a^\varepsilon(x) = \phi_a^\varepsilon(x)$ for

almost every $0 < x < a$. Conversely, equality (4.3) shows that every solution of (4.2) on $(0, b)$ is determined by its restriction on $(0, a)$. Hence the uniqueness of solutions follows from Lemma 4.5. By the way of the extension, $\tilde{\phi}_a^\varepsilon$ is real-valued almost everywhere.

If $\omega > 1$, we obtain unique extended continuous solution $\tilde{\phi}_a^\varepsilon$ on $(0, \infty)$ by (4.3), since $h_\omega(x)$ is continuous on $(0, \infty)$ and $C^0(0, a) \subset L^2((0, a), dx)$. \square

In what follows, we denote by ϕ_a^ε the extended solution $\tilde{\phi}_a^\varepsilon$ for $a > 1$ if no confusion arise. For $0 < a \leq 1$, we take the convention that

$$\phi_a^+(x) = \phi_a^-(x) = h_\omega(ax) \quad x \in (0, \infty).$$

Obviously, these are continuous on $(0, \infty)$ if $\omega > 1$. This convention is compatible with Lemma 4.5 and 4.6, since integral equation (4.2) for $0 < a \leq 1$ should be $X(x) = h_\omega(ax)$ by Lemma 4.2, and $h_\omega(ax) = 0$ on $(0, a)$ for $0 < a \leq 1$. Then its extension $\tilde{\phi}_a^\varepsilon(x)$ to $(0, \infty)$ should be $h_\omega(ax)$ by (4.3).

§ 4.2. Differentiability of the solution

In this part, we handle the differentiability of the extended solution $\phi_a^\varepsilon(x)$ with respect to x and a under the restriction to the parameter $\omega > 1$. This restriction is required in order to obtain the continuity of the kernel $K(x, y) = h_\omega(xy)$.

Let $a > 1$. The solution ϕ_a^ε of (4.2) is related to the kernel of the resolvent $(1 - \lambda H_{\omega, a})^{-1}$ as follows. The kernel $K(x, y) = h_\omega(xy)$ of $H_{\omega, a}$ is continuous on $[0, a] \times [0, a]$ by the assumption $\omega > 1$. Then there exists a continuous function $R(x, y; \lambda; a)$ for $(x, y, \lambda) \in [0, a] \times [0, a] \times \mathbb{C}$ satisfying integral equations

$$(4.4) \quad \begin{aligned} R(x, y; \lambda; a) - \lambda \int_0^a K(x, z)R(z, y; \lambda; a) dz &= K(x, y), \\ R(x, y; \lambda; a) - \lambda \int_0^a K(z, y)R(x, z; \lambda; a) dz &= K(x, y) \end{aligned}$$

(see Smithies [25, Chap. V], Lax [19, Chap. 24], for example). By taking $y = a$ and $\lambda = -\varepsilon$ in the first equation of (4.4), we have

$$R(x, a; -\varepsilon; a) + \varepsilon \int_0^a h_\omega(xz)R(z, a; -\varepsilon; a) dz = h_\omega(ax).$$

Therefore, we obtain

$$(4.5) \quad \phi_a^\varepsilon(x) = R(x, a; -\varepsilon; a)$$

for $0 < x < a$ by the uniqueness of solutions of (4.2). In particular, we obtain the continuity of $\phi_a^\varepsilon(x)$ for x again, and

$$(4.6) \quad \lim_{a \rightarrow 1^+} \phi_a^\varepsilon(a) = \lim_{a \rightarrow 1^+} R(a, a; -\varepsilon; a) = 0$$

by Lemma 4.2. We investigate the differentiability of $\phi_a^\varepsilon(x)$ by using the resolvent kernel $R(x, y; \lambda; a)$. The following inequality is going to be used often.

Hadamard's inequality (see [25, Theorem 5.2.1], for example). Let $A = (a_{ij})$ be a $n \times n$ complex matrix. If $|a_{ij}| \leq M$ ($1 \leq i, j \leq n$), then $|\det A|^2 \leq n^n M^{2n}$.

We introduce the notation

$$K \begin{pmatrix} x_1, x_2, \dots, x_n \\ y_1, y_2, \dots, y_n \end{pmatrix} = \det \begin{pmatrix} K(x_1, y_1) & K(x_1, y_2) & \cdots & K(x_1, y_n) \\ K(x_2, y_1) & K(x_2, y_2) & \cdots & K(x_2, y_n) \\ \vdots & \vdots & \ddots & \vdots \\ K(x_n, y_1) & K(x_n, y_2) & \cdots & K(x_n, y_n) \end{pmatrix}$$

as usual. The Fredholm determinant $d(\lambda; a)$ and the first Fredholm minor $D(x, y; \lambda; a)$ of the continuous kernel $K(x, y)$ on $\Omega_a = [0, a] \times [0, a]$ are defined as follows:

$$(4.7) \quad d(\lambda; a) = \sum_{n=0}^{\infty} d_n(a) \lambda^n,$$

$$(4.8) \quad D(x, y; \lambda; a) = \sum_{n=0}^{\infty} D_n(x, y; a) \lambda^n,$$

where $d_0(a) = 1$, $D_0(x, y; a) = K(x, y)$ and

$$(4.9) \quad d_n(a) = \frac{(-1)^n}{n!} \int_0^a \cdots \int_0^a K \begin{pmatrix} x_1, x_2, \dots, x_n \\ x_1, x_2, \dots, x_n \end{pmatrix} dx_1 \dots dx_n \quad (n \geq 1),$$

$$(4.10) \quad D_n(x, y; a) = \frac{(-1)^n}{n!} \int_0^a \cdots \int_0^a K \begin{pmatrix} x, x_1, \dots, x_n \\ y, x_1, \dots, x_n \end{pmatrix} dx_1 \dots dx_n \quad (n \geq 1).$$

The kernel $D_n(x, y; a)$ are clearly continuous in (x, y) . It is well-known that the series (4.8) converges uniformly and absolutely in (x, y, λ) when λ is confined in a compact subset of \mathbb{C} , and $D(x, y; \lambda; a)$ is a continuous function on Ω_a for every $\lambda \in \mathbb{C}$ (see [25, Theorem 5.3.1], for example). If $d(\lambda; a) \neq 0$, the resolvent kernel $R(x, y; \lambda; a)$ is given by

$$(4.11) \quad R(x, y; \lambda; a) = \frac{D(x, y; \lambda; a)}{d(\lambda; a)}.$$

Note that $d(\pm 1; a) \neq 0$ for every $a > 1$ when $K(x, y) = h_\omega(xy)$ and $\omega > 1/2$ by Lemma 4.4 and Theorem 5.6.1 of [25].

Lemma 4.7. *Let $\omega > 1$, $a > 1$ and $\varepsilon \in \{\pm 1\}$. Then the extended solution $\phi_a^\varepsilon(x)$ is continuously differentiable on $x \in [0, \infty) \setminus \{n/a \mid n \in \mathbb{N}\}$.*

Proof. By (4.3), (4.5) and (4.11), it is sufficient to prove that the Fredholm minor $D(x, y; \lambda; a)$ for the kernel $K(x, y) = h_\omega(xy)$ on $\Omega_a = [0, a] \times [0, a]$ is continuously differentiable on $x \in D_a := [0, a] \setminus \{n/a \mid n \in \mathbb{N}\}$ for every fixed $y \in [0, a]$, since $h_\omega(ax)$ is continuously differentiable on $x \in [0, \infty) \setminus \{n/a \mid n \in \mathbb{N}\}$, and $|\frac{\partial}{\partial x} h_\omega(xy) \phi_a^\varepsilon(y)|$ is integrable on $[0, a]$. To prove it, we modify the proof of Theorem 5.3.1 in [25]. We have

$$\begin{aligned} K \begin{pmatrix} x, x_1, \dots, x_n \\ y, x_1, \dots, x_n \end{pmatrix} &= \det \begin{pmatrix} K(x, y) & K(x, x_1) & \cdots & K(x, x_n) \\ K(x_1, y) & K(x_1, x_1) & \cdots & K(x_1, x_n) \\ \vdots & \vdots & \ddots & \vdots \\ K(x_n, y) & K(x_n, x_1) & \cdots & K(x_n, x_n) \end{pmatrix} \\ &= K(x, y) K \begin{pmatrix} x_1, \dots, x_n \\ x_1, \dots, x_n \end{pmatrix} + \det \begin{pmatrix} 0 & K(x, x_1) & \cdots & K(x, x_n) \\ K(x_1, y) & K(x_1, x_1) & \cdots & K(x_1, x_n) \\ \vdots & \vdots & \ddots & \vdots \\ K(x_n, y) & K(x_n, x_1) & \cdots & K(x_n, x_n) \end{pmatrix}. \end{aligned}$$

Therefore, by (4.9) and (4.10), we have

$$\begin{aligned} \frac{\partial}{\partial x} D_n(x, y; a) &= d_n(a) \frac{\partial}{\partial x} K(x, y) \\ &+ \frac{(-1)^n}{n!} \int_0^a \cdots \int_0^a \det \begin{pmatrix} 0 & \frac{\partial}{\partial x} K(x, x_1) & \cdots & \frac{\partial}{\partial x} K(x, x_n) \\ K(x_1, y) & K(x_1, x_1) & \cdots & K(x_1, x_n) \\ \vdots & \vdots & \ddots & \vdots \\ K(x_n, y) & K(x_n, x_1) & \cdots & K(x_n, x_n) \end{pmatrix} dx_1 \cdots dx_n \\ &= d_n(a) \frac{\partial}{\partial x} K(x, y) + D_n^\dagger(x, y; a), \end{aligned}$$

say. Then, we obtain

$$\frac{\partial}{\partial x} D(x, y; \lambda; a) = d(\lambda; a) \frac{\partial}{\partial x} K(x, y) + \sum_{n=0}^\infty D_n^\dagger(x, y; a) \lambda^n$$

by (4.8). The first term on the right-hand side is continuous on $x \in D_a$. Therefore, in order to prove the existence and the continuity of $\frac{\partial}{\partial x} D(x, y; \lambda; a)$ on $x \in D_a$, it is sufficient to prove that the series on the right-hand side converges uniformly on every compact subset in D_a . Put

$$M_1(a) = a \sup_{(x,y) \in \Omega_a} |K(x, y)|, \quad M_2(a) = \sup_{x \in [0, a]} \int_0^a \left| \frac{\partial}{\partial x} K(x, y) \right| dy.$$

The second constant $M_2(a)$ is well-defined, since $\int_0^a \left| \frac{\partial}{\partial x} K(x, y) \right| dy = \int_0^a |h'_\omega(xy)| y dy$ is continuous on $[0, a]$ (by $\omega > 1$). Using the row expansion of the determinant and

Hadamard’s inequality, we have

$$\left| \det \begin{pmatrix} 0 & \frac{\partial}{\partial x} K(x, x_1) \cdots \frac{\partial}{\partial x} K(x, x_n) \\ K(x_1, y) & K(x_1, x_1) \cdots K(x_1, x_n) \\ \vdots & \vdots \quad \ddots \quad \vdots \\ K(x_n, y) & K(x_n, x_1) \cdots K(x_n, x_n) \end{pmatrix} \right| \leq n^{\frac{1}{2}n} \left(\frac{M_1(a)}{a} \right)^n \sum_{j=1}^n \left| \frac{\partial}{\partial x} K(x, x_j) \right|.$$

Therefore, we obtain

$$\begin{aligned} |D_n^\dagger(x, y; a)| &\leq \frac{n^{\frac{1}{2}n}}{n!} \left(\frac{M_1(a)}{a} \right)^n \int_0^a \cdots \int_0^a \sum_{j=1}^n \left| \frac{\partial}{\partial x} K(x, x_j) \right| dx_1 \cdots dx_n \\ &= \frac{n^{\frac{1}{2}n}}{an!} M_1(a)^n \sum_{j=1}^n \int_0^a \left| \frac{\partial}{\partial x} K(x, x_j) \right| dx_j \leq \frac{M_2(a)}{a} \frac{n^{\frac{1}{2}n} M_1(a)^n}{(n-1)!}. \end{aligned}$$

Therefore, the series $\sum_{n=0}^\infty D_n^\dagger(x, y; a)\lambda^n$ converges uniformly and absolutely in $(x, y, \lambda) \in \Omega_a \times \mathbb{C}$, when λ is contained in a compact subset of \mathbb{C} . Hence, for fixed $y \in [0, a]$, $D(x, y; \lambda; a) - d(\lambda; a)K(x, y)$ is a continuously differentiable function on $[0, a]$ such that

$$\frac{\partial}{\partial x} \left(D(x, y; \lambda; a) - d(\lambda; a)K(x, y) \right) = \sum_{n=0}^\infty D_n^\dagger(x, y)\lambda^n.$$

We complete the proof of the lemma. □

Lemma 4.8. *Let $\omega > 1$ and $\varepsilon \in \{\pm 1\}$. Then the extended solution $\phi_a^\varepsilon(x)$ is continuous in $a \in (1, \infty)$ for every fixed $x > 0$. In addition, it is continuously differentiable with respect to a in $(1, \infty) \setminus \{n/x, \sqrt{n} \mid n \in \mathbb{N}\}$.*

Proof. The continuity in a follows from (4.3) and (4.5). Before the proof of the differentiability, we note that $d(\lambda, a)$ is continuous in a . In fact, we have

$$|d_n(a)| \leq \frac{n^{\frac{1}{2}n} M_1(a)^n}{n!} \left(M_1(a) = a \sup_{(x,y) \in \Omega_a} |K(x, y)| \right)$$

by definition (4.9) and Hadamard’s inequality, and hence the series of (4.7) converges absolutely and uniformly on a compact subset of $(\lambda, a) \in \mathbb{C} \times (1, \infty)$.

Let $\lambda \in \mathbb{C}$ such that $d(\lambda; a) \neq 0$ for every $a > 1$. We have

$$\frac{\partial}{\partial a} R(x, a; \lambda; a) = \frac{\frac{\partial}{\partial a} D(x, a; \lambda; a)d(\lambda; a) - D(x, a; \lambda; a)\frac{\partial}{\partial a} d(\lambda; a)}{d(\lambda; a)^2}$$

by (4.11). Therefore, in order to prove the lemma, we need (i) the existence and the continuity of $\frac{\partial}{\partial a} d(\lambda; a)$ and (ii) the existence, the continuity and the integrability of $\frac{\partial}{\partial a} D(x, a; \lambda; a)$ by (4.3), (4.5) and

$$\frac{\partial}{\partial a} \int_0^a h_\omega(xy)\phi_a^\varepsilon(y) dy = h_\omega(ax)\phi_a^\varepsilon(a) + \int_0^a h_\omega(xy)\frac{\partial}{\partial a}\phi_a^\varepsilon(y) dy.$$

We prove (i). By definition (4.7) and (4.9), we have

$$\begin{aligned} \frac{\partial}{\partial a}d(\lambda; a) &= -\lambda K(a, a) + \sum_{n=2}^{\infty} \frac{(-\lambda)^n}{n!} \left\{ \int_0^a \cdots \int_0^a K \begin{pmatrix} a, x_2, \cdots, x_n \\ a, x_2, \cdots, x_n \end{pmatrix} dx_2 \cdots dx_n \right. \\ &\quad + \sum_{k=2}^{n-1} \int_0^a \cdots \int_0^a K \begin{pmatrix} x_1, \cdots, x_{k-1}, a, x_{k+1}, \cdots, x_n \\ x_1, \cdots, x_{k-1}, a, x_{k+1}, \cdots, x_n \end{pmatrix} dx_1 \cdots dx_{k-1} dx_{k+1} \cdots dx_n \\ &\quad \left. + \int_0^a \cdots \int_0^a K \begin{pmatrix} x_1, x_2, \cdots, x_{n-1}, a \\ x_1, x_2, \cdots, x_{n-1}, a \end{pmatrix} dx_1 \cdots dx_{n-1} \right\}. \end{aligned}$$

Clearly, each term in the series is continuous in a , since $K(x, y)$ is continuous. By using Hadamard’s inequality,

$$\left| \frac{\partial}{\partial a}d(\lambda; a) \right| \leq \sum_{n=1}^{\infty} \frac{|\lambda|^n}{n!} n^{\frac{1}{2}n} \left(\frac{M_1(a)}{a} \right)^n na^{n-1} = \frac{1}{a} \sum_{n=1}^{\infty} \frac{n^{\frac{1}{2}n}}{(n-1)!} (|\lambda|M_1(a))^n.$$

The series on the right-hand side converges uniformly on a compact subset of $(\lambda, a) \in \mathbb{C} \times [0, \infty)$. Hence $d(\lambda; a)$ is continuously differentiable for a .

Successively, we prove (ii). we have

$$\frac{\partial}{\partial a}D(x, a; \lambda; a) = D_y(x, a; \lambda; a) + D_a(x, a; \lambda; a),$$

where D_y (resp. D_a) means the partial derivative with respect to the second (resp. the fourth) variable. We find that $D(x, y; \lambda; a)$ is continuously differentiable with respect to $y \in [0, \infty) \setminus \{n/a \mid n \in \mathbb{N}\}$, and $D_y(x, y; \lambda; a)$ is a continuous function on $(x, y) \in [0, \infty) \times ([0, \infty) \setminus \{n/a \mid n \in \mathbb{N}\})$ by a way similar to the proof of Lemma 4.7. Thus $D_y(x, a; \lambda; a)$ is continuous on $a \in (1, \infty) \setminus \{\sqrt{n} \mid n \in \mathbb{N}\}$ for fixed x , and $|D_y(x, a; \lambda; a)|$ is integrable on $[0, a]$ with respect to x . On the other hand, by definition (4.8) and (4.10),

$$\begin{aligned} \frac{\partial}{\partial a}D(x, y; \lambda; a) &= -\lambda K(a, a)K(x, y) + \lambda K(x, a)K(a, y) \\ &\quad + \sum_{n=2}^{\infty} \frac{(-\lambda)^n}{n!} \left\{ \int_0^a \cdots \int_0^a K \begin{pmatrix} x, a, x_2, \cdots, x_n \\ y, a, x_2, \cdots, x_n \end{pmatrix} dx_2 \cdots dx_n \right. \\ &\quad + \sum_{k=2}^{n-1} \int_0^a \cdots \int_0^a K \begin{pmatrix} x, x_1, \cdots, x_{k-1}, a, x_{k+1}, \cdots, x_n \\ y, x_1, \cdots, x_{k-1}, a, x_{k+1}, \cdots, x_n \end{pmatrix} dx_1 \cdots dx_{k-1} dx_{k+1} \cdots dx_n \\ &\quad \left. + \int_0^a \cdots \int_0^a K \begin{pmatrix} x, x_1, \cdots, x_{n-1}, a \\ y, x_1, \cdots, x_{n-1}, a \end{pmatrix} dx_1 \cdots dx_{n-1} \right\}. \end{aligned}$$

Clearly, each term in the series is continuous in (x, y, a) , since $K(x, y)$ is continuous.

By the row expansion of the determinant and Hadamard’s inequality, we obtain

$$\begin{aligned} \left| \frac{\partial}{\partial a} D(x, y; \lambda; a) \right| &\leq \sum_{n=1}^{\infty} \frac{|\lambda|^n}{n!} n^{\frac{1}{2}n} \left(\frac{M_1(a)}{a} \right)^n \int_0^a \cdots \int_0^a \sum_{j=1}^n |K(x, x_j)| dx_1 \cdots dx_{n-1} \\ &= \frac{1}{a^2} \int_0^a |K(x, x_1)| dx_1 \sum_{n=1}^{\infty} \frac{n^{\frac{1}{2}n}}{(n-1)!} (|\lambda| M_1(a))^n. \end{aligned}$$

when $0 \leq y \leq a$. The series on the right-hand side converges uniformly on a compact subset of $(\lambda, a) \in \mathbb{C} \times (1, \infty)$. Thus $D_a(x, a; \lambda; a)$ is continuous in a . In addition, the right-hand side shows that $|D_a(x, a; \lambda; a)|$ is integrable on $[0, a]$ with respect to x .

Hence $\frac{\partial}{\partial a} R(x, a; \lambda; a)$ is continuous on $a \in (1, \infty) \setminus \{\sqrt{n} \mid n \in \mathbb{N}\}$ for fixed x , and $|\frac{\partial}{\partial a} R(x, a; \lambda; a)|$ is integrable on $[0, a]$ with respect to x . As a consequence we obtain the lemma by (4.3) and (4.5). □

§ 4.3. The first order differential system

As in the previous section, we assume that $\omega > 1$. Then Θ_ω is an inner function in \mathbb{C}^+ , the kernel $h_\omega(xy)$ of \mathbf{H}_ω or $\mathbf{H}_{\omega,a}$ is continuous, and $\phi_a^\varepsilon(x)$ is continuously differentiable with respect to x and a outside loci $ax = k$ ($k \in \mathbb{N}$). Under this situation, we derive a first order differential system arising from ϕ_a^ε ($a > 1, \varepsilon \in \{\pm 1\}$) start from

$$(4.12) \quad \phi_a^\varepsilon(x) + \varepsilon \int_0^a h_\omega(xy) \phi_a^\varepsilon(y) dy = h_\omega(ax).$$

Firstly, we operate $a \frac{\partial}{\partial a}$ on both side of (4.12). Then,

$$\begin{aligned} a \frac{\partial}{\partial a} \phi_a^\varepsilon(x) + \varepsilon a \frac{\partial}{\partial a} \int_0^a h_\omega(xy) \phi_a^\varepsilon(y) dy &= a \frac{\partial}{\partial a} h_\omega(ax); \\ a \frac{\partial}{\partial a} \phi_a^\varepsilon(x) + \varepsilon a \phi_a^\varepsilon(a) h_\omega(ax) + \varepsilon \int_0^a h_\omega(xy) a \frac{\partial}{\partial a} \phi_a^\varepsilon(y) dy &= a \frac{\partial}{\partial a} h_\omega(ax); \\ (4.13) \quad a \frac{\partial}{\partial a} \phi_a^\varepsilon(x) + \varepsilon \int_0^a h_\omega(xy) a \frac{\partial}{\partial a} \phi_a^\varepsilon(y) dy &= -\varepsilon a \phi_a^\varepsilon(a) h_\omega(ax) + a \frac{\partial}{\partial a} h_\omega(ax). \end{aligned}$$

Secondly, we operate $x \frac{\partial}{\partial x}$ on both side of (4.12):

$$x \frac{\partial}{\partial x} \phi_a^\varepsilon(x) + \varepsilon x \frac{\partial}{\partial x} \int_0^a h_\omega(xy) \phi_a^\varepsilon(y) dy = x \frac{\partial}{\partial x} h_\omega(ax) = a \frac{\partial}{\partial a} h_\omega(ax).$$

Using the identity $x \frac{\partial}{\partial x} h_\omega(xy) = y \frac{\partial}{\partial y} h_\omega(xy)$ and then applying integration by parts to the integral of the left-hand side, we have

$$x \frac{\partial}{\partial x} \phi_a^\varepsilon(x) + \varepsilon a \phi_a^\varepsilon(a) h_\omega(ax) - \varepsilon \int_0^a h_\omega(xy) \frac{\partial}{\partial y} (y \phi_a^\varepsilon(y)) dy = a \frac{\partial}{\partial a} h_\omega(ax).$$

Putting $\delta_x = x \frac{\partial}{\partial x} + \frac{1}{2} = \frac{\partial}{\partial x} x - \frac{1}{2}$, we obtain

$$(4.14) \quad \begin{aligned} \delta_x \phi_a^\varepsilon(x) - \frac{1}{2} \phi_a^\varepsilon(x) - \varepsilon \int_0^a h_\omega(xy) \left(\delta_y \phi_a^\varepsilon(y) + \frac{1}{2} \phi_a^\varepsilon(y) \right) dy \\ = -\varepsilon a \phi_a^\varepsilon(a) h_\omega(ax) + a \frac{\partial}{\partial a} h_\omega(ax). \end{aligned}$$

Next, we rewrite the left-hand side of (4.14) as follows by using (4.12) for the second term of the left-hand side:

$$(4.15) \quad \begin{aligned} \delta_x \phi_a^\varepsilon(x) - \frac{1}{2} \left(h_\omega(ax) - \varepsilon \int_0^a h_\omega(xy) \phi_a^\varepsilon(y) dy \right) - \varepsilon \int_0^a h_\omega(xy) \left(\delta_y \phi_a^\varepsilon(y) + \frac{1}{2} \phi_a^\varepsilon(y) \right) dy \\ = \delta_x \phi_a^\varepsilon(x) - \frac{1}{2} h_\omega(ax) - \varepsilon \int_0^a h_\omega(xy) \delta_y \phi_a^\varepsilon(y) dy. \end{aligned}$$

Substituting the right-hand side of (4.15) for the left-hand side of (4.14) and rearranging, we obtain

$$(4.16) \quad \delta_x \phi_a^\varepsilon(x) - \varepsilon \int_0^a h_\omega(xy) \delta_y \phi_a^\varepsilon(y) dy = \left(\frac{1}{2} - \varepsilon a \phi_a^\varepsilon(a) \right) h_\omega(ax) + a \frac{\partial}{\partial a} h_\omega(ax).$$

Subtracting (4.16) with choice $-\varepsilon$ from (4.13) with ε , we obtain

$$(4.17) \quad \begin{aligned} \left\{ a \frac{\partial}{\partial a} \phi_a^\varepsilon(x) - \delta_x \phi_a^{-\varepsilon}(x) \right\} + \varepsilon \int_0^a h_\omega(xy) \left\{ a \frac{\partial}{\partial a} \phi_a^\varepsilon(y) - \delta_y \phi_a^{-\varepsilon}(y) \right\} dy \\ = - \left(\frac{1}{2} + \varepsilon \mu(a) \right) h_\omega(ax), \end{aligned}$$

where

$$(4.18) \quad \mu(a) = a \phi_a^+(a) + a \phi_a^-(a).$$

By (4.6), Lemma 4.7 and 4.8, the function $\mu(a)$ is continuous on $(1, \infty)$, which satisfies $\lim_{a \rightarrow 1^+} \mu(a) = 0$, and is continuously differentiable on $(1, \infty) \setminus \{\sqrt{n} \mid n \in N\}$.

Equality (4.17) shows that $a \frac{\partial}{\partial a} \phi_a^\varepsilon(x) - \delta_x \phi_a^{-\varepsilon}(x)$ is a continuous solution of (4.12). Hence, by comparing (4.12) with (4.17), we obtain

$$(4.19) \quad a \frac{\partial}{\partial a} \phi_a^\varepsilon(x) - \delta_x \phi_a^{-\varepsilon}(x) = - \left(\frac{1}{2} + \varepsilon \mu(a) \right) \phi_a^\varepsilon(x) \quad (\varepsilon \in \{\pm 1\})$$

by the uniqueness of solutions (Lemmas 4.5 and 4.6). We use (4.19) in the form

$$(4.20) \quad \left(a \frac{\partial}{\partial a} + \frac{1}{2} + \varepsilon \mu(a) \right) \phi_a^\varepsilon(x) = \delta_x \phi_a^{-\varepsilon}(x) \quad (\varepsilon \in \{\pm 1\}).$$

Now we introduce two special functions

$$\begin{aligned}
 \tilde{A}_a(z) &:= \frac{a^{iz}}{2} + \frac{\sqrt{a}}{2} \int_a^\infty \phi_a^+(x) x^{\frac{1}{2}+iz} \frac{dx}{x} = \frac{a^{iz}}{2} + \frac{\sqrt{a}}{2} F_{1/2}(1 - P_a)\phi_a^+(z), \\
 -i\tilde{B}_a(z) &:= \frac{a^{iz}}{2} - \frac{\sqrt{a}}{2} \int_a^\infty \phi_a^-(x) x^{\frac{1}{2}+iz} \frac{dx}{x} = \frac{a^{iz}}{2} - \frac{\sqrt{a}}{2} F_{1/2}(1 - P_a)\phi_a^-(z)
 \end{aligned}
 \tag{4.21}$$

for $\Im(z) \gg 0$ and $a > 1$. These functions are defined as analytic functions for large $\Im(z) > 0$ by integrals, since ϕ_a^\pm are continuous and have at most polynomial growth at $+\infty$ by (4.12) and the rough estimate

$$\begin{aligned}
 h_\omega(x) &= \frac{1}{2\pi} \int_{-U+ic}^{U+ic} \Theta_\omega(z) x^{-\frac{1}{2}-iz} dz + O(x^{c-\frac{1}{2}}U^{1-\omega}) \quad (c > 1/2 + \omega) \\
 &= O(x^{c-\frac{1}{2}}U) + O(x^{c-\frac{1}{2}}U^{1-\omega}) = O(x^{\omega+\epsilon}).
 \end{aligned}
 \tag{4.22}$$

As shown below, \tilde{A}_a and \tilde{B}_a are analytically continuable to meromorphic functions in \mathbb{C} . We put it off a little and derive a differential system satisfied by \tilde{A}_a and \tilde{B}_a . Using (4.20), we have

$$\begin{aligned}
 \left(a \frac{\partial}{\partial a} + \mu(a)\right) \tilde{A}_a(z) &= (iz + \mu(a)) \frac{a^{iz}}{2} + \left(a \frac{\partial}{\partial a} + \mu(a)\right) \frac{\sqrt{a}}{2} \int_a^\infty \phi_a^+(x) x^{\frac{1}{2}+iz} \frac{dx}{x} \\
 &= (iz + \mu(a)) \frac{a^{iz}}{2} - \frac{\sqrt{a}}{2} \phi_a^+(a) a^{\frac{1}{2}+iz} + \frac{\sqrt{a}}{2} \int_a^\infty \left(a \frac{\partial}{\partial a} + \frac{1}{2} + \mu(a)\right) \phi_a^+(x) x^{\frac{1}{2}+iz} \frac{dx}{x} \\
 &= (iz + \mu(a)) \frac{a^{iz}}{2} - \frac{\sqrt{a}}{2} \phi_a^+(a) a^{\frac{1}{2}+iz} + \frac{\sqrt{a}}{2} \int_a^\infty \left(x \frac{\partial}{\partial x} + \frac{1}{2}\right) \phi_a^-(x) x^{\frac{1}{2}+iz} \frac{dx}{x} \\
 &= iz \frac{a^{iz}}{2} - iz \frac{\sqrt{a}}{2} \int_a^\infty \phi_a^-(x) x^{\frac{1}{2}+iz} \frac{dx}{x} = z \tilde{B}_a(z)
 \end{aligned}$$

for large $\Im(z) > 0$, and then it holds for all $z \in \mathbb{C}$ by meromorphic continuation (below). We obtain a similar formula for $(a \frac{\partial}{\partial a} + \mu(a))\tilde{B}_a$. As a result, we obtain the first order differential system

$$- \begin{bmatrix} a \frac{\partial}{\partial a} + \mu(a) & 0 \\ 0 & a \frac{\partial}{\partial a} - \mu(a) \end{bmatrix} \begin{bmatrix} \tilde{A}_a(z) \\ \tilde{B}_a(z) \end{bmatrix} = z \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \tilde{A}_a(z) \\ \tilde{B}_a(z) \end{bmatrix} \quad (a > 1).
 \tag{4.23}$$

We extend the system to $a > 0$ by taking the convention that

$$\mu(a) = 0
 \tag{4.24}$$

and

$$\begin{aligned}
 \tilde{A}_a(z) &= \frac{a^{iz}}{2} + \frac{\sqrt{a}}{2} \int_{1/a}^\infty h_\omega(ax) x^{\frac{1}{2}+iz} \frac{dx}{x} = \frac{1}{2} \left(a^{iz} + \Theta_\omega(z) a^{-iz} \right), \\
 -i\tilde{B}_a(z) &= \frac{a^{iz}}{2} - \frac{\sqrt{a}}{2} \int_{1/a}^\infty h_\omega(ax) x^{\frac{1}{2}+iz} \frac{dx}{x} = \frac{1}{2} \left(a^{iz} - \Theta_\omega(z) a^{-iz} \right)
 \end{aligned}
 \tag{4.25}$$

for $0 < a \leq 1$. Actually the convention (4.24) and (4.25) for $0 < a \leq 1$ is compatible with Lemma 4.2 and the convention mentioned in the end of Section 4.1.

For $a > 0$, we define

$$(4.26) \quad \begin{aligned} A_a(z) &= m(a) \xi \left(\frac{1}{2} + \omega - iz \right) \tilde{A}_a(z), \\ B_a(z) &= \frac{1}{m(a)} \xi \left(\frac{1}{2} + \omega - iz \right) \tilde{B}_a(z) \end{aligned}$$

with

$$(4.27) \quad m(a) = \exp \left(\int_1^a \mu(b) \frac{db}{b} \right) \quad \left(\mu(a) = a \frac{d}{da} \log m(a) \right)$$

under (4.24) and (4.25). Note that $m(a)$ is real-valued by its definition. Then we can verify that system (4.23) implies that (A_a, B_a) satisfies the canonical system

$$(4.28) \quad -a \frac{\partial}{\partial a} \begin{bmatrix} X_a(z) \\ Y_a(z) \end{bmatrix} = z \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} m(a)^{-2} & 0 \\ 0 & m(a)^2 \end{bmatrix} \begin{bmatrix} X_a(z) \\ Y_a(z) \end{bmatrix} \quad (0 < a < \infty)$$

by elementary ways. It is concluded that (4.28) is the canonical system of Theorem 2.3 if formula

$$m(a) = \frac{\det(1 + H_{\omega,a})}{\det(1 - H_{\omega,a})}$$

is proved for $a > 1$, since $\frac{\det(1+H_{\omega,a})}{\det(1-H_{\omega,a})} = 1$ for $0 < a \leq 1$ by Lemma 4.2. This will follow from showing

$$(4.29) \quad \begin{aligned} \phi_a^+(a) &= \frac{d}{da} \log \det(1 + H_{\omega,a}), \\ \phi_a^-(a) &= -\frac{d}{da} \log \det(1 - H_{\omega,a}) \end{aligned}$$

by definition (4.18) and (4.27). This is a well-known formula for an integral operator defined on a finite interval with a continuous kernel. In fact, it is proved by a way similar to the proof of Theorem 12 of Chapter 24 in [19]. (This also holds for $0 < a < 1$, since $\phi_a^\pm(a) = h_\omega(a^2) = 0$ by the convention in the end of Section 4.1 and $\log \det(1 \pm H_{\omega,a}) = 0$ by Lemma 4.2.)

For every fixed $0 < a \leq 1$, A_a and B_a are real entire functions satisfying $A_a(-z) = A_a(z)$ and $B_a(-z) = -B_a(z)$, respectively, by (4.25), (4.26) and functional equations $\xi(s) = \xi(1 - s)$ and $\xi(s) = \overline{\xi(\bar{s})}$. Successively, we prove that A_a and B_a have these properties for $a > 1$.

§ 4.4. Meromorphic continuation and functional equations

Under assumptions and notations of Section 4.3, we define

$$\begin{aligned}
 \tilde{E}_a(z) &:= \tilde{A}_a(z) - i\tilde{B}_a(z) \\
 &= a^{iz} + \frac{\sqrt{a}}{2} \int_a^\infty (\phi_a^+(x) - \phi_a^-(x)) x^{\frac{1}{2}+iz} \frac{dx}{x} \\
 &= a^{iz} + \frac{\sqrt{a}}{2} F_{1/2}(1 - P_a)(\phi_a^+ - \phi_a^-)(z) \\
 \tilde{E}_a^*(z) &:= \tilde{A}_a(z) + i\tilde{B}_a(z) \\
 &= \frac{\sqrt{a}}{2} \int_a^\infty (\phi_a^+(x) + \phi_a^-(x)) x^{\frac{1}{2}+iz} \frac{dx}{x} \\
 &= \frac{\sqrt{a}}{2} F_{1/2}(1 + P_a)(\phi_a^+ + \phi_a^-)(z)
 \end{aligned}
 \tag{4.30}$$

for $\Im(z) \gg 0$ and $a > 1$. We deal with A_a, B_a via $\tilde{E}_a(z)$ and $\tilde{E}_a^*(z)$.

Lemma 4.9. *Let $\omega > 1$ and $a > 1$. Define*

$$\Psi_a(z) = \int_a^\infty (\phi_a^+(x) - \phi_a^-(x)) x^{\frac{1}{2}+iz} \frac{dx}{x}.
 \tag{4.31}$$

Then integral of (4.31) converges absolutely for $\Im(z) > 0$ and converges in the L^2 -sense on $\Im(z) = 0$. Moreover $\Psi_a(z)$ is extended to a meromorphic function in \mathbb{C} which is analytic in \mathbb{C}^+ .

Proof. By (4.12), we have

$$\phi_a^+ - \phi_a^- = -H_\omega P_a(\phi_a^+ + \phi_a^-),
 \tag{4.32}$$

where $P_a(\phi_a^+ + \phi_a^-)$ has compact support in $[1/a, a]$. Therefore $\phi_a^+ - \phi_a^-$ belongs to $L^2((\alpha, \infty), dx)$ for every $\alpha > 0$. Hence integral (4.31) converges absolutely for $\Im(z) > 0$ and defines a function of H^2 ([29, Chap. II, §10]). Using (4.32), we have

$$\begin{aligned}
 \Psi_a(z) &= F_{1/2}(1 - P_a)(\phi_a^+ - \phi_a^-)(z) \\
 &= -F_{1/2}(1 - P_a)H_\omega P_a(\phi_a^+ + \phi_a^-)(z) \\
 &= -F_{1/2}H_\omega P_a(\phi_a^+ + \phi_a^-)(z) + F_{1/2}P_aH_\omega P_a(\phi_a^+ + \phi_a^-)(z)
 \end{aligned}$$

for $\Im(z) \gg 0$. Here $P_a(\phi_a^+ + \phi_a^-)$ and $P_aH_\omega P_a(\phi_a^+ + \phi_a^-)$ have compact support in $(0, \infty)$. Therefore, we obtain

$$\Psi_a(z) = -\Theta_\omega(z)F_{1/2}P_a(\phi_a^+ + \phi_a^-)(-z) + F_{1/2}P_aH_\omega P_a(\phi_a^+ + \phi_a^-)(z),
 \tag{4.33}$$

where $F_{1/2}P_a(\phi_a^+ + \phi_a^-)(-z)$ and $F_{1/2}P_aH_\omega P_a(\phi_a^+ + \phi_a^-)(z)$ are entire functions. Hence $\Psi_a(z)$ is extended to a meromorphic function on \mathbb{C} , and is analytic in \mathbb{C}^+ by (4.33), since $\Theta_\omega(z)$ is a meromorphic inner function in \mathbb{C}^+ . \square

Lemma 4.10. *Let $\omega > 1$ and $a > 1$. Functions \tilde{E}_a and \tilde{E}_a^* of (4.30) are analytically continuable to meromorphic functions in \mathbb{C} satisfying $\tilde{E}_a^*(z) = \Theta_\omega(z)\tilde{E}_a(-z)$, and they are analytic in \mathbb{C}^+ . Moreover, both $\xi(\frac{1}{2} + \omega - iz)\tilde{E}_a(z)$ and $\xi(\frac{1}{2} + \omega - iz)\tilde{E}_a^*(z)$ are entire functions.*

Proof. We have

$$(4.34) \quad \mathbf{H}_\omega \mathbf{P}_a(\phi_a^+ - \phi_a^-)(x) = 2h_\omega(ax) - \phi_a^+(x) - \phi_a^-(x)$$

by (4.12). Using (1.8), (4.32), and (4.33), we have

$$\begin{aligned} \Theta_\omega(z)\tilde{E}_a(-z) &= \Theta_\omega(z)a^{-iz} + \Theta_\omega(z)\frac{\sqrt{a}}{2}\Psi_a(-z) \\ &\stackrel{(4.33)}{=} \Theta_\omega(z)a^{-iz} - \Theta_\omega(z)\Theta_\omega(-z)\frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) \\ &\quad + \frac{\sqrt{a}}{2}\Theta_\omega(z)\mathbf{F}_{1/2}\mathbf{P}_a\mathbf{H}_\omega\mathbf{P}_a(\phi_a^+ + \phi_a^-)(-z) \\ &\stackrel{(1.8)}{=} \Theta_\omega(z)a^{-iz} - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) \\ &\quad + \Theta_\omega(z)\frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a\mathbf{H}_\omega\mathbf{P}_a(\phi_a^+ + \phi_a^-)(-z) \\ &\stackrel{(4.32)}{=} \Theta_\omega(z)a^{-iz} - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) \\ &\quad - \Theta_\omega(z)\frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ - \phi_a^-)(-z) \end{aligned}$$

for $z \in \mathbb{C}$, since $\mathbf{P}_a(\phi_a^+ \pm \phi_a^-)$, and $\mathbf{P}_a\mathbf{H}_\omega\mathbf{P}_a(\phi_a^+ + \phi_a^-)$ have compact support. Further, by Proposition 2.1, Lemma 4.1, and (4.34), we have

$$\begin{aligned} \Theta_\omega(z)\tilde{E}_a(-z) &= \Theta_\omega(z)a^{-iz} - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) \\ &\quad - \Theta_\omega(z)\frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ - \phi_a^-)(-z) \\ &\stackrel{(4.1)}{=} \Theta_\omega(z)a^{-iz} - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{H}_\omega\mathbf{P}_a(\phi_a^+ - \phi_a^-)(z) \\ &\stackrel{(4.34)}{=} \Theta_\omega(z)a^{-iz} - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) \\ &\quad - \sqrt{a}\mathbf{F}_{1/2}(h_\omega(ax))(z) + \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}(\phi_a^+ + \phi_a^-)(z) \\ &\stackrel{(2.4)}{=} \Theta_\omega(z)a^{-iz} - \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}\mathbf{P}_a(\phi_a^+ + \phi_a^-)(z) \\ &\quad - \Theta_\omega(z)a^{-iz} + \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}(\phi_a^+ + \phi_a^-)(z) \\ &= \frac{\sqrt{a}}{2}\mathbf{F}_{1/2}(1 - \mathbf{P}_a)(\phi_a^+ + \phi_a^-)(z) = \tilde{E}_a^*(z) \end{aligned}$$

for $\Im(z) \gg 0$, since $\phi_a^+ + \phi_a^-$ is identically zero on $(0, 1/a)$ and has polynomial growth at $x = +\infty$. Hence $\tilde{E}_a^*(z) = \Theta_\omega(z)\tilde{E}_a(-z)$ for $\Im(z) \gg 0$. By Lemma 4.9, $\tilde{E}_a(z)$ is meromorphic in \mathbb{C} , therefore, $\tilde{E}_a^*(z)$ is also analytically continuable to a meromorphic function in \mathbb{C} . Moreover, $\tilde{E}_a(z) = \Theta_\omega(z)(\text{entire}) + (\text{entire})$ from the proof of Lemma 4.9. Thus

$$\tilde{E}_a^*(z) = \Theta(z)\tilde{E}_a(-z) = (\text{entire}) + \Theta_\omega(z)(\text{entire})$$

by (1.8), and hence $\tilde{E}_a^*(z)$ is analytic in \mathbb{C}^+ . Simultaneously, these equalities show that $\xi(\frac{1}{2} + \omega - iz)\tilde{E}_a(z)$ and $\xi(\frac{1}{2} + \omega - iz)\tilde{E}_a^*(z)$ are entire by definition of $\Theta_\omega(z)$. \square

Lemma 4.10 implies the following immediately.

Lemma 4.11. *Let $\omega > 1$ and $a > 1$. Then $\tilde{A}_a(z)$ and $\tilde{B}_a(z)$ are analytically continuable to meromorphic functions in \mathbb{C} , and they are analytic in \mathbb{C}^+ . Also, $A_a(z)$ and $B_a(z)$ are both entire functions. In addition, we have functional equations*

$$\begin{aligned} \Theta_\omega(z)\tilde{A}_a(-z) &= \tilde{A}_a(z), & \Theta_\omega(z)\tilde{B}_a(-z) &= -\tilde{B}_a(z), \\ A_a(-z) &= A_a(z), & B_a(-z) &= -B_a(z). \end{aligned}$$

Proof. We have $2\tilde{A}_a = \tilde{E}_a + \tilde{E}_a^*$ and $-2i\tilde{B}_a = \tilde{E}_a - \tilde{E}_a^*$ by definition (4.30). Therefore, they are analytically continuable to meromorphic function in \mathbb{C} and satisfy $2\tilde{A}_a(z) = \tilde{E}_a(z) + \Theta_\omega(z)\tilde{E}_a(-z)$ and $-2i\tilde{B}_a(z) = \tilde{E}_a(z) - \Theta_\omega(z)\tilde{E}_a(-z)$ by Lemma 4.10. That imply the functional equations stated in the lemma. Other things are consequences of Lemma 4.10. \square

Lemma 4.12. *Let $\omega > 1$ and $a > 1$. Then $A_a(z)$ and $B_a(z)$ are real entire functions.*

Proof. At first, we note that if $F(z) = \mathbf{F}_{1/2}(f(x))(z)$ for $\Im(z) \gg 0$, then $F^\sharp(z) = \mathbf{F}_{1/2}(x^{-1}\overline{f(x^{-1})})(z)$ and $F(-z) = \mathbf{F}_{1/2}(x^{-1}f(x^{-1}))(z)$ for $\Im(z) \ll 0$. Therefore, if $f(x)$ (resp. $if(x)$) is real-valued, $F(z)$ is analytically continued to a meromorphic function in \mathbb{C} , and $F(-z) = F(z)$ (resp. $F(-z) = -F(z)$), then $F^\sharp(z) = F(z)$ holds for $z \in \mathbb{C}$. Let

$$\phi(x) := \frac{1}{2} \frac{d}{dx} \left(x^2 \frac{d}{dx} \theta(x^2) \right) = 2 \sum_{n=1}^{\infty} (2\pi^2 n^4 x^4 - 3\pi n^2 x^2) \exp(-\pi n^2 x^2).$$

Then $\phi(1/x) = x\phi(x)$ and $\xi(s) = \int_0^\infty \phi(x)x^s \frac{dx}{x}$ for every $s \in \mathbb{C}$ ([27, §10.1]). Hence $\xi(\frac{1}{2} + \omega - iz) = \mathbf{F}_{1/2}(x^{-\omega}\phi(x))(z)$ for $z \in \mathbb{C}$. On the other hand, by (4.21), $\tilde{A}_a(z) = \mathbf{F}_{1/2}(\frac{\sqrt{a}}{2}(\delta_a + (1 - P_a)\phi_a^+))(z)$ and $\tilde{B}_a(z) = \mathbf{F}_{1/2}(\frac{i\sqrt{a}}{2}(\delta_a - (1 - P_a)\phi_a^-))(z)$ for $\Im(z) \gg 0$, where $\delta_a(x)$ is the Dirac delta-function at $x = a$. Therefore $A_a(z) = \mathbf{F}_{1/2}(f^+(x))(z)$

and $B_a(z) = F_{1/2}(f^-(x))(z)$ for

$$\begin{aligned} f^+(x) &:= \frac{m(a)\sqrt{a}}{2} \int_0^\infty (x/y)^{-\omega} \phi(x/y)(\delta_a(y) + (1 - P_a)\phi_a^+(y)) \frac{dy}{y} \\ &= \frac{m(a)x^{-\omega}}{2} \left(a^{\omega-\frac{1}{2}}\phi(x/a) + \sqrt{a} \int_a^\infty \phi(x/y)\phi_a^+(y) y^{\omega-1} dy \right), \\ f^-(x) &:= \frac{i\sqrt{a}}{2m(a)} \int_0^\infty (x/y)^{-\omega} \phi(x/y)(\delta_a(y) - (1 - P_a)\phi_a^-(y)) \frac{dy}{y} \\ &= \frac{ix^{-\omega}}{2m(a)} \left(a^{\omega-\frac{1}{2}}\phi(x/a) - \sqrt{a} \int_a^\infty \phi(x/y)\phi_a^-(y) y^{\omega-1} dy \right) \end{aligned}$$

if $\Im(z) \gg 0$. Here $f^+(x)$ and $if^-(x)$ are both real-valued, since $m(a)$ is real, and $\phi(x)$, $\phi_a^\pm(x)$ are real-valued. In addition, $A_a(-z) = A_a(z)$ and $B_a(-z) = -B_a(z)$ for $z \in \mathbb{C}$ by Lemma 4.11. Hence $A_a^\sharp = A_a$ and $B_a^\sharp = B_a$. □

Now we complete the proof of Theorem 2.3 (1), (2). The remaining assertion is (3). In order to prove it, we show the following lemma.

Lemma 4.13. *Let $\omega > 1$. Then*

$$(4.35) \quad \lim_{a \rightarrow 1^+} A_a(z) = A^\omega(z), \quad \lim_{a \rightarrow 1^+} B_a(z) = B^\omega(z)$$

hold uniformly on every compact subset in \mathbb{C} .

Proof. By (4.2) and (4.3), $\phi_a^\pm(x) \rightarrow h_\omega(x)$ uniformly on $[1/2, 3/2]$ as $a \rightarrow 1^+$. Therefore, by (4.30) and (4.33), $\tilde{E}_a(z)$ converges to a meromorphic function in \mathbb{C} uniformly on every compact subset in \mathbb{C} as $a \rightarrow 1^+$, since $P_a(\phi_a^+ + \phi_a^-)(-z)$ and $P_a H_\omega P_a(\phi_a^+ + \phi_a^-)(z)$ both have support in $[1/a, a]$. On the other hand, we have

$$(4.36) \quad \phi_a^+(x) - \phi_a^-(x) = - \int_{1/a}^a h_\omega(xz)(\phi_a^+(z) + \phi_a^-(z)) dz$$

by (4.12), since $\phi_a^\pm(x) = 0$ for $0 < x < 1/a$. Multiplying by x^{-v} on both sides of (4.36), and then tending $a \rightarrow 1^+$, we have

$$\lim_{a \rightarrow 1^+} (\phi_a^+(x) - \phi_a^-(x))x^{-v} = 0$$

uniformly on $(1, \infty)$ if $v > 0$ is large, since h_ω is of polynomial growth at $+\infty$. Hence $\lim_{a \rightarrow 1^+} \tilde{E}_a(z) = 1$ uniformly on every compact subset in $\Im(z) > v$. As a consequence $\lim_{a \rightarrow 1^+} \tilde{E}_a(z) = 1$, and

$$\lim_{a \rightarrow 1^+} \tilde{A}_a(z) = \frac{1}{2}(1 + \Theta_\omega(z)), \quad \lim_{a \rightarrow 1^+} \tilde{B}_a(z) = \frac{i}{2}(1 - \Theta_\omega(z))$$

uniformly on every compact subset in \mathbb{C} . Multiplying by $\xi(\frac{1}{2} + \omega - iz)$ on both sides of these equalities, we obtain (4.35) by (4.6) and (4.26). \square

By definition, we have $m(a) = 1$ and

$$\begin{aligned} A_a(z) &= \xi\left(\frac{1}{2} + \omega - iz\right) a^{iz} + \xi\left(\frac{1}{2} - \omega - iz\right) a^{-iz}, \\ B_a(z) &= \xi\left(\frac{1}{2} + \omega - iz\right) a^{iz} - \xi\left(\frac{1}{2} - \omega - iz\right) a^{-iz} \end{aligned}$$

for $0 < a \leq 1$. This shows $(A_1, B_1) = (A^\omega, B^\omega)$ and $\lim_{a \rightarrow 1^-} (A_a(z), B_a(z)) = (A^\omega(z), B^\omega(z))$ uniformly on every compact subset in \mathbb{C} . Together with Lemma 4.13, we obtain Theorem 2.3 (3), and hence we complete the proof of Theorem 2.3.

§ 5. Comments on the validity of Theorem 2.3

In this section, we comment on a range of $\omega > 0$ where Theorem 2.3 is expected to be extended. There might be three levels of difficulties at least: (i) $\omega > 1/2$, (ii) $\omega = 1/2$, (iii) $0 < \omega < 1/2$.

It is natural to expect that Theorem 2.3 is proved unconditionally for the range (i) as mentioned after Theorem 2.3. In fact, all lemmas in Section 4.1 are already proved for $\omega > 1/2$. Therefore, the remaining problems are a proof of the differentiability of $\phi_a^\varepsilon(x)$ with respect to x and a , and formula of $m(a)$ by determinants. However, if we understand partial derivatives $\frac{\partial}{\partial x} \phi_a^\varepsilon(x)$ and $\frac{\partial}{\partial a} \phi_a^\varepsilon(x)$ in the sense of distributions as in Burnol [6], and if we use the theory of Fredholm determinants for L^2 -kernels ([25, Chap. VI]), then most of Section 4.3 and 4.4 have reasonable meaning, and we may obtain Theorem 2.3 for $\omega > 1/2$. This way is plausible, and must be carried out after a suitable preparation for the theory of distributions.

The case (ii) have more difficulties, because the kernel of $H_{\omega,a}$ is no longer Hilbert-Schmidt type. However, $\Theta_\omega(z)$ is still inner function in \mathbb{C}^+ unconditionally. Therefore, problems may be restricted to the theory of integral operators, its determinants, and the theory of integral equations only as well as the case (i). See the later half of comments on (iii) below.

It is easily predicted that it is very hard to generalize Theorem 2.3 to the range (iii) unconditionally. A reason of difficulties is that problems of arithmetic and analysis are mixed in this range. However, if we assume RH, the function Θ_ω is inner in \mathbb{C}^+ for every $\omega > 0$, and hence remaining problems may be restricted to the theory of integral operators and the theory of integral equations only. Such analytic problems may be solved without essential difficulties.

In fact, if $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ , H_ω is extended to an isometry on $L^2((0, \infty), dx)$ by Lemma 4.1. On the other hand, $H_{\omega,a}$ is a compact operator on $L^2((0, a), dx)$ even for (iii) (and (ii)) because its kernel is a sum of finitely many weakly singular kernels. Therefore, in particular, the Fredholm alternative holds. Hence we may obtain reasonable generalization of results in Section 4.1 for $\omega > 0$ under RH, and then throughout distribution theoretic dealing of Section 4.3 and 4.4, we may arrive at the generalization of Theorem 2.3 for the range (iii) (and (ii)) under RH. In this strategy, it is necessary to note that $\phi_a^\varepsilon(x)$ have some possible singularities, which affect definition (4.18) of $\mu(a)$ and definition (4.27) of $m(a)$, and that the definition of determinants $\det(1 \pm H_{\omega,a})$ should be changed as in König [14].

We leave a justification of the above argument for a future study.

§ Appendix A.

Suppose that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ . (It holds unconditionally for $\omega \geq 1/2$, and also for $0 < \omega < 1/2$ under RH.) Then it defines the reproducing kernel Hilbert space $K(\Theta_\omega)$ which is isomorphic to the de Branges space $B(E^\omega)$ (see Section 1.3 and 1.4). According to the theory of de Branges [9], the structure of $B(E^\omega)$ is determined by associated canonical system, which was described in terms of the shifted Fourier inversion $h_\omega(x)$ of $\Theta_\omega(z)$ under the restriction $\omega > 1$. On the other hand, the structure of $B(E^\omega)$ is also determined by the reproducing kernel of $K(\Theta_\omega)$:

$$K_\omega(z, w) = \frac{1}{2\pi i} \frac{1 - \overline{\Theta_\omega(z)}\Theta_\omega(w)}{\bar{z} - w} \quad (z, w \in \mathbb{C}^+)$$

(see Section 1.3). We find that $K_\omega(0, *)$ belongs to $L^2(\mathbb{R})$ by (1.9) and (1.10), and thus its shifted Fourier inversion $F_{1/2}^{-1}K_\omega(0, *)$ belongs to $L^2((0, \infty), dx)$.

However, if we obtain $F_{1/2}^{-1}K_\omega(0, *)$ explicitly enough, we may define $F_{1/2}^{-1}K_\omega(0, *)$ regardless whether $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ . In fact, it is carried out by using the weighted summatory function $h_\omega^{(1)}(x)$ defined below. Then sufficient or equivalent conditions for $\Theta_\omega(z)$ to be an inner function in \mathbb{C}^+ are given in terms of $h_\omega^{(1)}(x)$ as in Theorem 2.2. This is the main result in the appendix.

The function $h_\omega^{(1)}(x)$ is not only directly related to RH via the innerness of $\Theta_\omega(z)$, but also directly related to the operator H_ω (Theorem A.2). The above discussion clarifies the meaning of a part of functions studied in [26] (see the remark after Theorem A.1).

A.1. Notation and Results

Let $B(z; p, q)$ be the incomplete beta function defined by

$$B(z; p, q) = \int_0^z x^{p-1}(1-x)^{q-1} dx \quad (0 \leq z \leq 1, \Re(p) > 0, \Re(q) > 0).$$

We use the notation

$$\beta(z; p, q) := B(p, q) - B(z; p, q) = \int_z^1 x^{p-1}(1-x)^{q-1} dx,$$

and understand that $\beta(z; p, q)$ is defined by the integral on the right-hand side if $\Re(p) \leq 0$, $\Re(q) > 0$, and $0 < z < 1$. For example, g_ω of (2.2) can be written as

$$g_\omega(x) = \frac{2\pi^\omega}{\Gamma(\omega)} \left[x^{2-\omega}(1-x^2)^{\omega-1} - \omega x^{\omega-1} \beta \left(x^2, \frac{3-2\omega}{2}, \omega \right) \right].$$

We define the real-valued function $g_\omega^{(1)}$ on $(0, \infty)$ by

$$(A.1) \quad g_\omega^{(1)}(x) := \int_x^1 \sqrt{\frac{y}{x}} g_\omega(y) \frac{dy}{y}$$

for $0 < x < 1$, and $g_\omega^{(1)}(x) = 0$ for $x > 1$. Then we have

$$g_\omega^{(1)}(x) = \begin{cases} \frac{4\omega}{2\omega-1} \frac{\pi^\omega}{\Gamma(\omega)} \left\{ x^{\omega-1} \beta \left(x^2, \frac{3-2\omega}{2}, \omega \right) - \frac{2\omega+1}{4\omega} x^{-1/2} \beta \left(x^2, \frac{5-2\omega}{4}, \omega \right) \right\}, & \omega \neq \frac{1}{2}, \\ \frac{2}{\sqrt{x}} \left(2\sqrt{1-x^2} + \log x - \log(1 + \sqrt{1-x^2}) \right), & \omega = \frac{1}{2} \end{cases}$$

for $0 < x < 1$ by elementary ways. Using $g_\omega^{(1)}$ and $c_\omega(n)$ of (2.1), we define the real-valued function $h_\omega^{(1)}$ on $(0, \infty)$ by

$$(A.2) \quad h_\omega^{(1)}(x) = \frac{1}{x} \sum_{n=1}^{\lfloor x \rfloor} c_\omega(n) g_\omega^{(1)} \left(\frac{n}{x} \right)$$

for $x > 1$, and $h_\omega^{(1)}(x) = 0$ for $0 < x < 1$. Then $h_\omega^{(1)}$ is well-defined on $(0, \infty)$ and has a support in $[1, \infty)$ as well as h_ω . We also have

$$(A.3) \quad h_\omega^{(1)}(x) = \int_1^x \sqrt{\frac{y}{x}} h_\omega(y) \frac{dy}{y}$$

for $x > 1$ by definition (A.1). The function $h_\omega^{(1)}$ is related to $K_\omega(z, w)$ and Θ_ω as follows.

Theorem A.1. *Let $\omega > 0$.*

(1) *If $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ , we have*

$$F_{1/2}^{-1} K_\omega(0, *) (z) = \frac{1}{2\pi} \left(x^{-\frac{1}{2}} \mathbf{1}_{(1, \infty)}(x) - h_\omega^{(1)}(x) \right),$$

where $\mathbf{1}_{(1, \infty)}$ is the characteristic function of $(1, \infty)$.

- (2) $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ if and only if $(x^{-\frac{1}{2}}\mathbf{1}_{(1,\infty)}(x) - h_\omega^{\langle 1 \rangle}(x))$ belongs to $L^2((1, \infty), dx)$.
- (3) Assume that there exists $x_\omega \geq 1$ such that $h_\omega^{\langle 1 \rangle}(x)$ has a single sign for every $x \geq x_\omega$. Then $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ .
- (4) Assume that $\lim_{x \rightarrow \infty} \sqrt{x} h_\omega^{\langle 1 \rangle}(x)$ exists. Then $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ .
- (5) Assume that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ for all $\omega > 0$. Then we have

$$\sqrt{x}h_\omega^{\langle 1 \rangle}(x) = 1 + o(1)$$

as $x \rightarrow +\infty$ for all $\omega > 0$.

Remark. The case $\lim_{x \rightarrow \infty} \sqrt{x} h_\omega^{\langle 1 \rangle}(x) = 0$ is allowed in (4), though it does not hold by (5) if RH holds for $\zeta(s)$.

Remark. Functions $h_\omega(x)$ of (2.3) and $h_\omega^{\langle 1 \rangle}(x)$ of (A.2) were introduced and studied in [26] for more general L -functions, but notation is different a little. The function $h_\omega^{\langle 1 \rangle}(x)$ (resp. $h_\omega(x)$) was denoted by $x^{-\frac{1}{2}}h_{1,\omega}^{\langle 1 \rangle}(x)$ (resp. $x^{-\frac{1}{2}}h_{1,\omega}^{\langle 0 \rangle}(x)$) in [26].

Theorem A.2. Suppose that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ . We define

$$(\tilde{H}_\omega f)(x) = \sqrt{x} \frac{d}{dx} \sqrt{x} \int_0^\infty h_\omega^{\langle 1 \rangle}(xy) f(y) dy$$

for compactly supported smooth functions f . Then $\tilde{H}_\omega f$ belongs to $L^2((0, \infty), dx)$, and $f \mapsto \tilde{H}_\omega f$ is extended to the isometry on $L^2((0, \infty), dx)$ satisfying $\tilde{H}_\omega f = H_\omega f$.

A.2. Proof of Theorem A.1

We prove each statement of Theorem A.1 separately. At first, we note the following:

Proposition A.3. For $\omega > 0$ and $\Im(z) > 1/2 + \omega$, we have

$$(A.4) \quad \int_0^\infty h_\omega^{\langle 1 \rangle}(x) x^{\frac{1}{2}+iz} \frac{dx}{x} = \frac{i}{z} \Theta_\omega(z),$$

where the integral converges absolutely.

Proof. This is proved by a way similar to the proof of Proposition 2.1 in Section 3.1 (see also Lemma 4.2 of [26]). □

(3): By the assumption and a theorem of Landau (e.g. Widder [29, Chap.II,§5]), the integral in (A.4) converges for $\Im(z) > v_0$, where iv_0 is the first pure imaginary

singularity of $\Theta_\omega(z)/z$. On the other hand, $\Theta_\omega(z)$ has no singularities on the imaginary axis, because it is known that $\xi(s)$ has no real zeros. Hence $\Theta_\omega(z)$ is regular in \mathbb{C}^+ . It implies that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ by a way similar to the proof of Lemma 3.1. □

(1) and (2): Suppose that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ . We have

$$h_\omega^{\langle 1 \rangle}(x) = \frac{1}{2\pi} \lim_{U \rightarrow \infty} \int_{-U+ic}^{U+ic} \frac{\Theta_\omega(z)}{-iz} x^{-\frac{1}{2}-iz} dz \quad (c > 1/2 + \omega)$$

for $x > 1$ by the Mellin inversion formula (e.g. [28, Theorem 28]), since the integral in (2.4) converges absolutely for $\Im(z) > 1/2 + \omega$ and $h_\omega^{\langle 1 \rangle}(x)$ is in $C^1(1, \infty)$. By the Stirling formula, we have $\Theta_\omega(u + iv) \ll_{\omega, v} u^{-\omega}$ for a fixed $v > 1/2 + \omega$. Therefore

$$h_\omega^{\langle 1 \rangle}(x) = \frac{1}{2\pi} \int_{-U+ic}^{U+ic} \frac{\Theta_\omega(z)}{-iz} x^{-\frac{1}{2}-iz} dz + O(x^{c-\frac{1}{2}}U^{-\omega}) \quad (c > 1/2 + \omega).$$

Using the well-known formula

$$x^{-\frac{1}{2}} = \frac{1}{2\pi} \int_{-U+ic}^{U+ic} \frac{1}{-iz} x^{-\frac{1}{2}-iz} dz + O(x^{c-\frac{1}{2}}(\log x)^{-1}U^{-1})$$

for $x > 1$ and large $U > 1$, we have

$$x^{-\frac{1}{2}} - h_\omega^{\langle 1 \rangle}(x) = \frac{1}{2\pi} \int_{-U+ic}^{U+ic} \frac{1 - \Theta_\omega(z)}{-iz} x^{-\frac{1}{2}-iz} dz + O(x^{c-\frac{1}{2}}U^{-\omega}) + O(x^{c-\frac{1}{2}}(\log x)^{-1}U^{-1}).$$

Here the integrand $(1 - \Theta_\omega(z))/z$ is bounded on $\mathbb{C}^+ \cup \mathbb{R}$. Thus the residue theorem gives

$$x^{-\frac{1}{2}} - h_\omega^{\langle 1 \rangle}(x) = \frac{1}{2\pi} \int_{-U}^U \frac{1 - \Theta_\omega(z)}{-iz} x^{-\frac{1}{2}-iz} dz + O(x^{c-\frac{1}{2}}U^{-\omega}) + O(x^{c-\frac{1}{2}}(\log x)^{-1}U^{-1}),$$

since integrals on $\int_{\pm U+ic}^{\pm U+ic}$ are bounded by $x^{c-\frac{1}{2}}(\log x)^{-1}U^{-1}$. Tending U to $+\infty$ for fixed $x > 1$, we have

$$(A.5) \quad x^{-\frac{1}{2}} - h_\omega^{\langle 1 \rangle}(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1 - \Theta_\omega(u)}{-iu} x^{-\frac{1}{2}-iu} du \quad (x > 1).$$

This implies that $x^{-\frac{1}{2}}\mathbf{1}_{(1, \infty)}(x) - h_\omega^{\langle 1 \rangle}(x)$ belongs to $L^2((1, \infty), dx)$, since $(1 - \Theta_\omega(u))/u$ belongs to $L^2(\mathbb{R})$ by (1.9) and (1.10). In addition, (A.5) implies (1).

Suppose that $x^{-1/2}\mathbf{1}_{(1, \infty)} - h_\omega^{\langle 1 \rangle}$ belongs to $L^2((1, \infty), dx)$. Then the integral

$$(A.6) \quad \int_0^\infty \left[x^{-\frac{1}{2}}\mathbf{1}_{(1, \infty)}(x) - h_\omega^{\langle 1 \rangle}(x) \right] x^{\frac{1}{2}+iz} \frac{dx}{x}$$

converges on the real line in L^2 -sense, and converges absolutely for $\Im(z) > 0$ ([29, Chap.II, §10]). Hence integral (A.6) defines an analytic function in \mathbb{C}^+ . By Proposition A.3, integral (A.6) is equal to $(1 - \Theta_\omega(z))/(iz)$ for $\Im(z) > 1/2 + \omega$. Hence we find that $\Theta_\omega(z)$ is an analytic function in \mathbb{C}^+ , and it implies that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ as well as the proof of (3). \square

(4): By formula (A.3), the assumption implies that the integral of (2.4) converges at $z = 0$ in the sense

$$\lim_{T \rightarrow \infty} \int_1^T h_\omega(x) x^{\frac{1}{2} + i0} \frac{dx}{x}.$$

This implies that the integral of (2.4) converges for $\Im(z) > 0$, and defines an analytic function in \mathbb{C}^+ ([29, Chap.II, §1]). Hence $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ by (1.9). \square

(5): If $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ for all $\omega > 0$, $\text{RH}(A^\omega)$ holds for all $\omega > 0$. Hence RH holds by Proposition 1.1. Then we obtain (5) by a way similar to the proof of Theorem 2.3 (2-b) in [26]. \square

A.3. Proof of Theorem A.2

Suppose that $\Theta_\omega(z)$ is an inner function in \mathbb{C}^+ . Let f be a compactly supported smooth function. Put $F = F_{1/2}f$ and define

$$g(x) = \frac{1}{2\pi} \int_{c-i\infty}^{c+i\infty} \Theta_\omega(z) F(-z) x^{-\frac{1}{2} - iz} dz$$

for $c \geq 0$. Then the right-hand side is independent of $c \geq 0$ by the assumption, and defines an member of $L^2((0, \infty), dx)$ by (1.9). Moreover, we have

$$\int_0^x \frac{g(u)}{\sqrt{u}} du = \frac{1}{2\pi} \int_{c-i\infty}^{c+i\infty} \Theta_\omega(z) F(-z) \frac{x^{-iz}}{-iz} dz.$$

for $c > 0$. On the other hand, by Proposition A.4, we obtain

$$\int_0^\infty h_\omega^{(1)}(xy) f(y) dy = \frac{1}{2\pi} \int_{c'-i\infty}^{c'+i\infty} \frac{\Theta_\omega(z)}{-iz} F(-z) x^{-\frac{1}{2} - iz} dz$$

for $c' \gg 0$. Hence

$$\frac{1}{\sqrt{x}} \int_0^x \frac{g(u)}{\sqrt{u}} du = \int_0^\infty h_\omega^{(1)}(xy) f(y) dy.$$

This implies that $g = \tilde{H}_\omega f$. Thus $\tilde{H}_\omega f$ is defined almost everywhere and belongs to $L^2((0, \infty), dx)$, since g belongs to $L^2((0, \infty), dx)$. Moreover we obtain $g = H_\omega f$ by the definition of g and the latter half of the proof of Lemma 4.1. Hence $\tilde{H}_\omega f = H_\omega f$, and it implies the extension of \tilde{H}_ω to $L^2((0, \infty), dx)$. \square

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